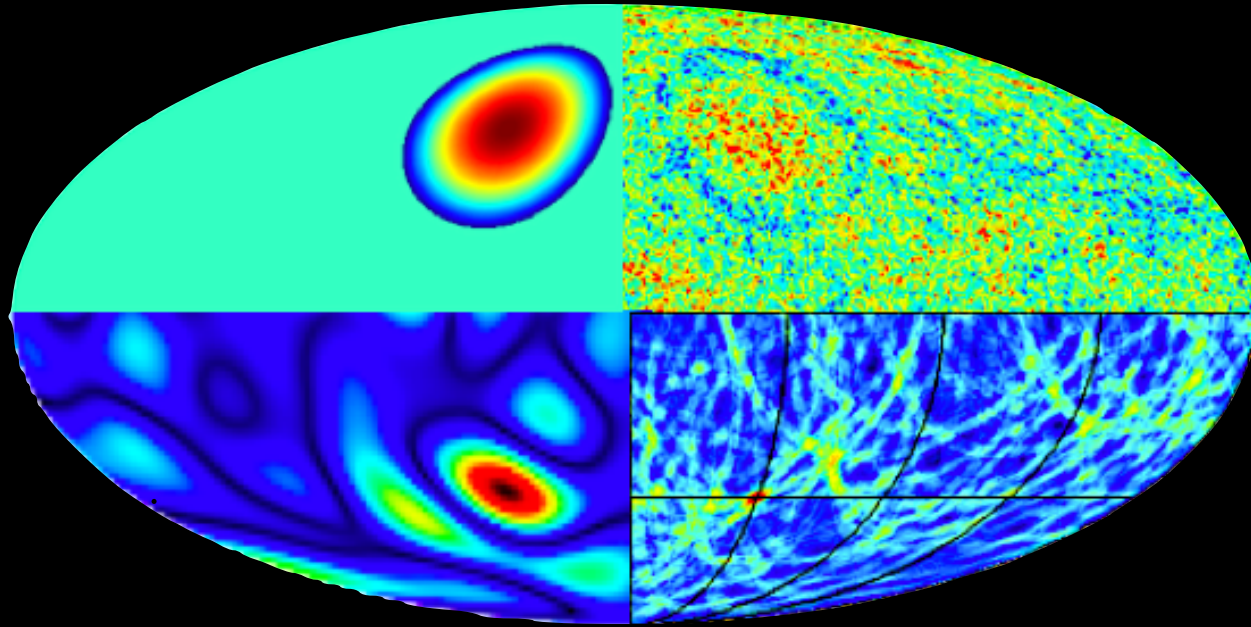


First observational tests of eternal inflation



Hiranya Peiris

University College London

arxiv:1012.1995, 1012.3667

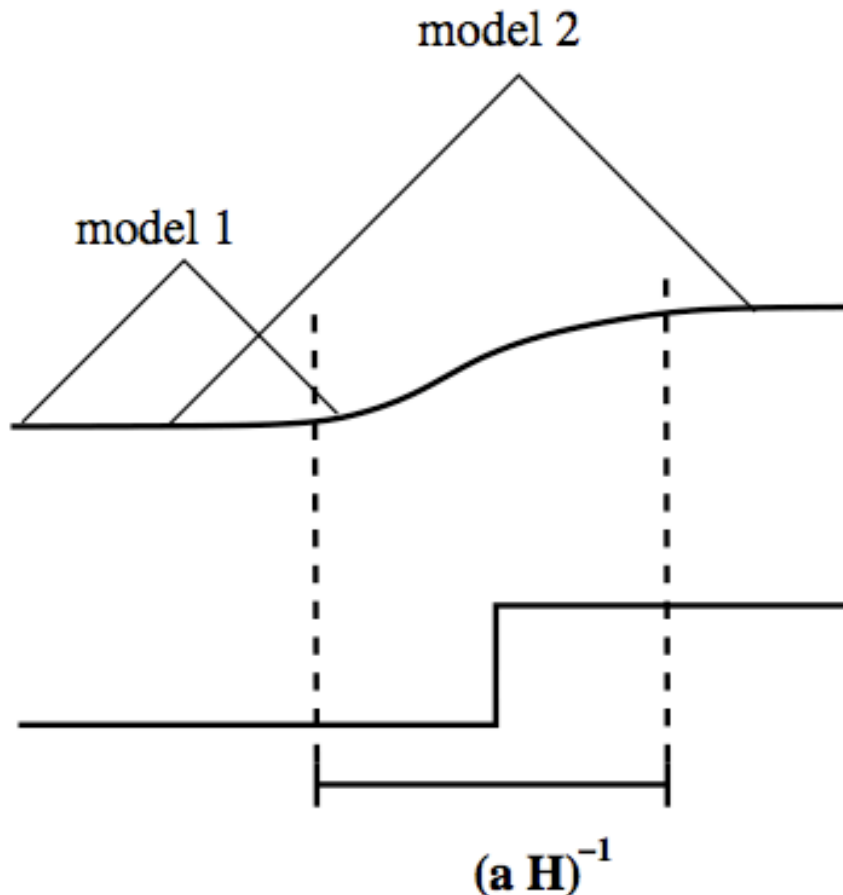
**With: Stephen Feeney (UCL), Matt Johnson (Perimeter Institute),
Daniel Mortlock (Imperial College London)**



Bubble morphologies

- Analysis will target following generic features expected in a collision (from analytic arguments backed up by simulations of Chang, Kleban & Levi.)

- ▶ Azimuthal symmetry
- ▶ Causal boundary (?)
- ▶ Long wavelength modulation inside the disk



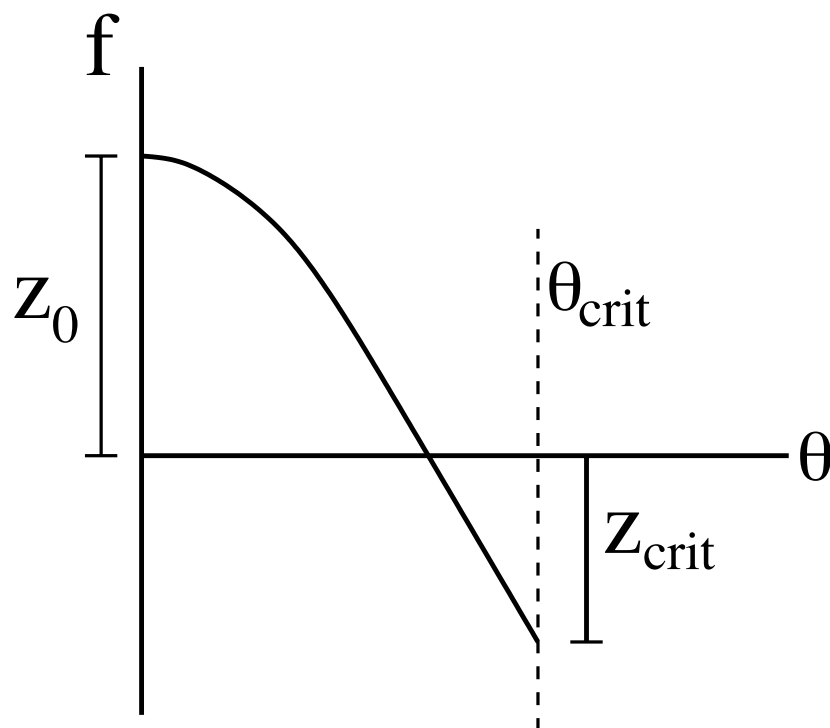
How a violent disturbance of the field at the collision is stretched and smoothed by inflation.

Bubble template

- Assume that the inflationary fluctuations are modulated by the collision (Chang et al 2009):

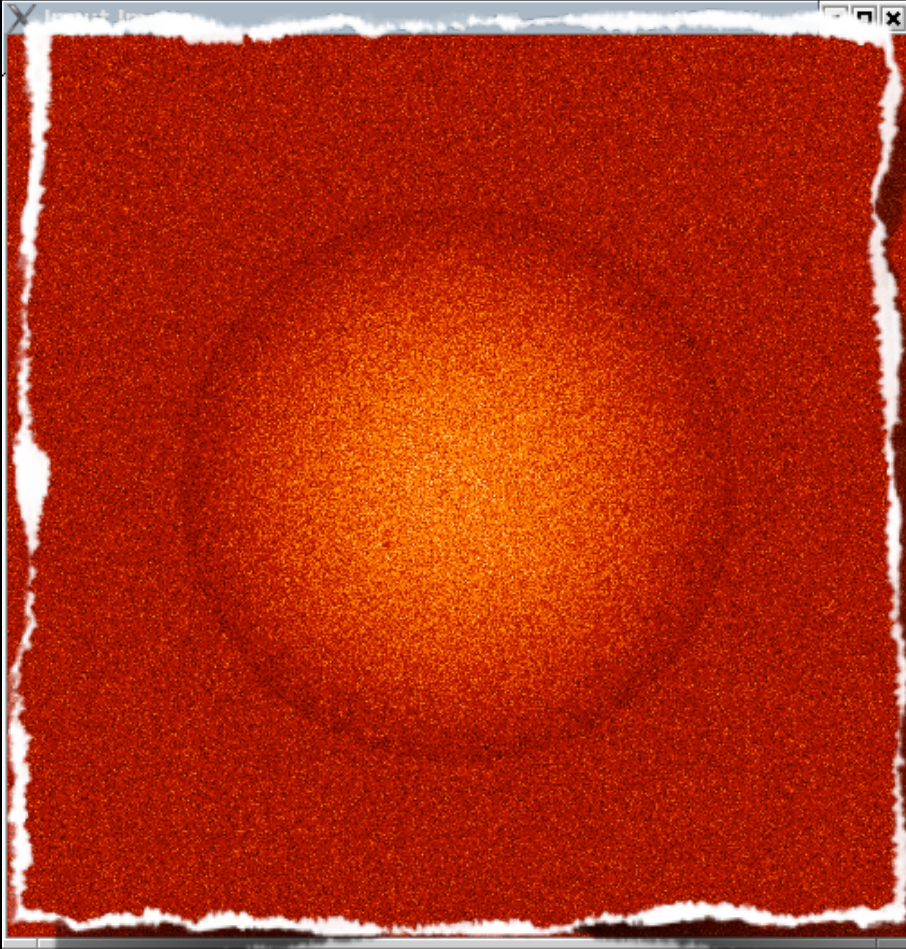
$$\frac{\delta T(\hat{\mathbf{n}})}{T_0} = (1 + f(\hat{\mathbf{n}}))(1 + \delta(\hat{\mathbf{n}})) - 1,$$

- Since the collision is a pre-inflationary relic, a reasonable template is: $f(\hat{n}) = (c_0 + c_1 \cos \theta + \mathcal{O}(\cos^2 \theta))\Theta(\theta_{\text{crit}} - \theta)$



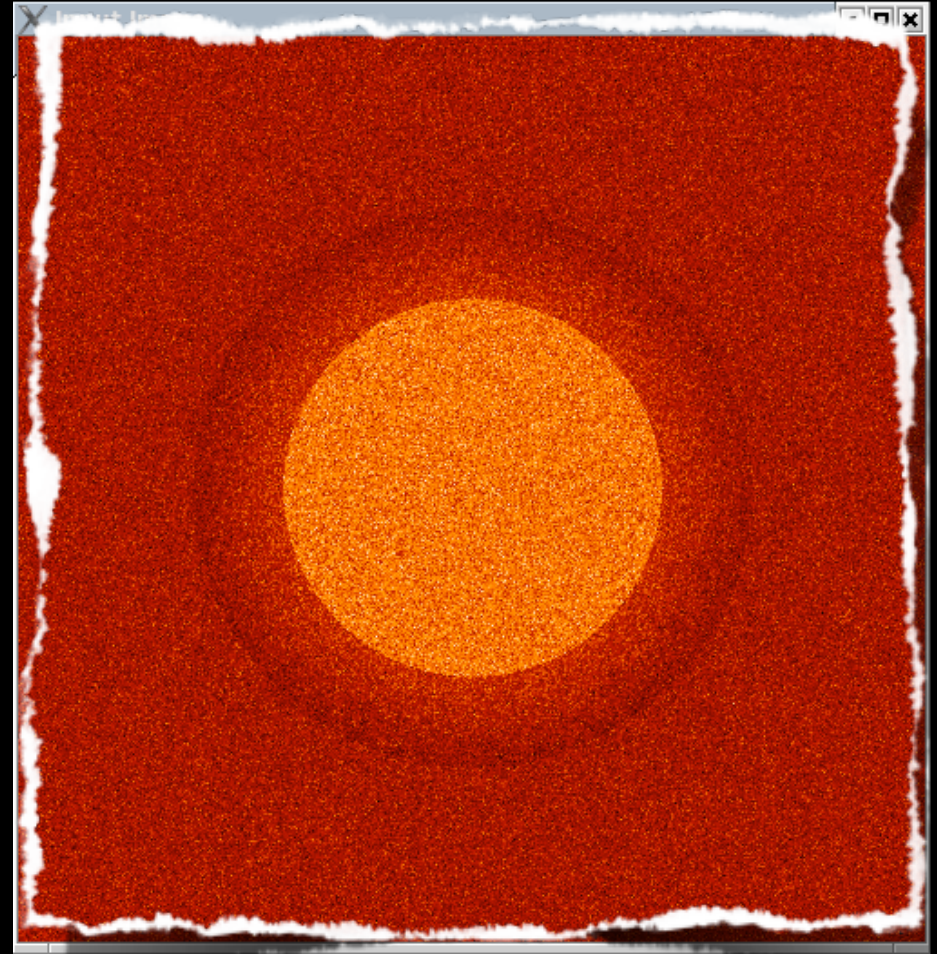
Bubble template

Model 1



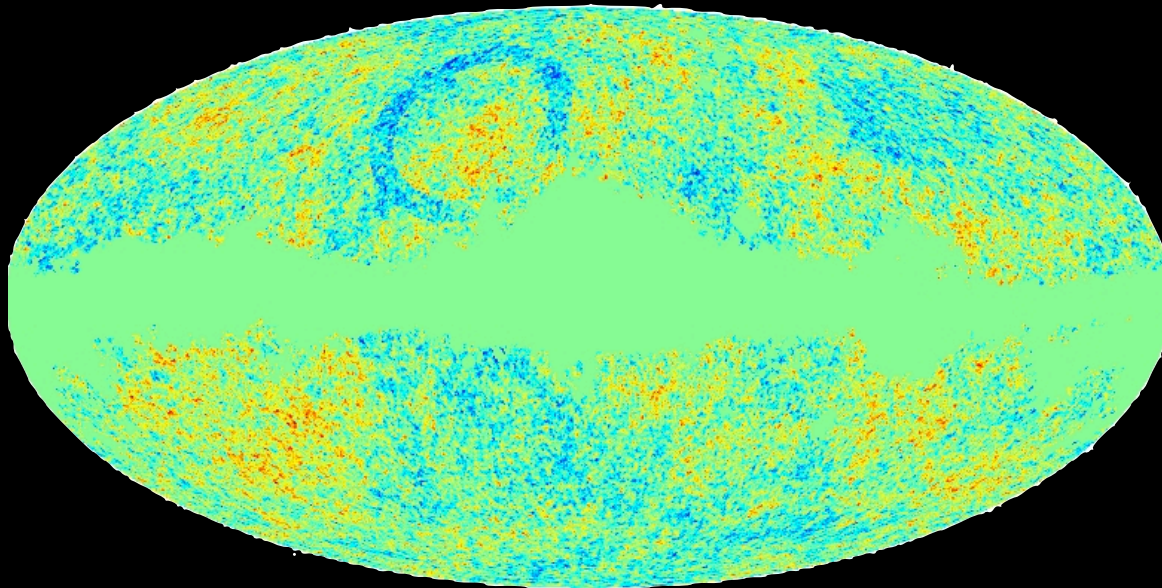
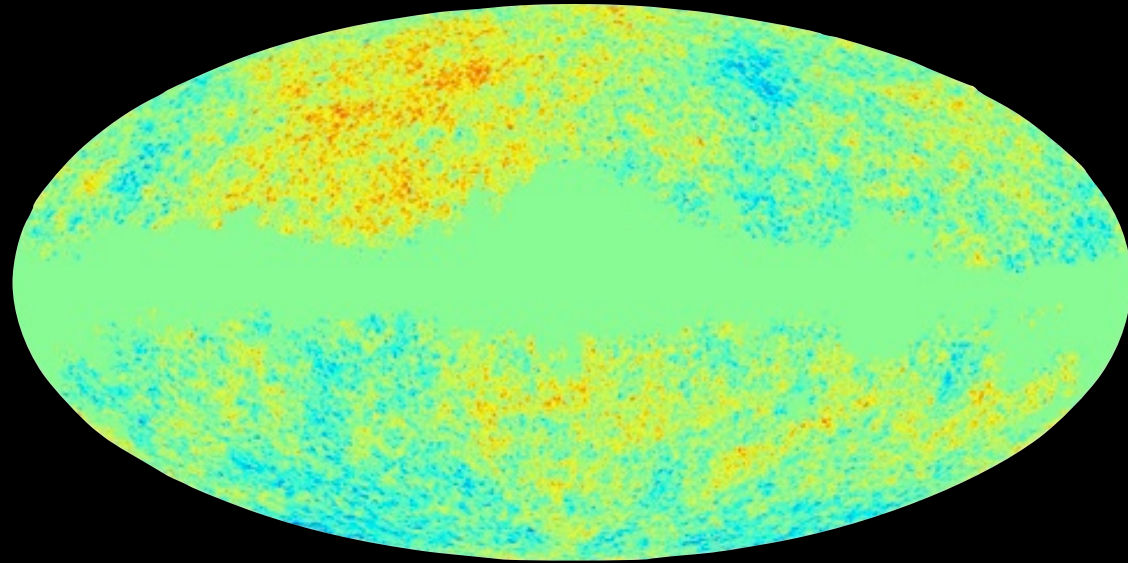
See small portion of smoothed collision

Model 2



See large portion of smoothed collision

Exaggerated CMB examples



Data Analysis Pipeline: Motivation I

- CMB is a large dataset. Easy to find “weird” features.
- *A posteriori* statistics promote high p -values and wrong inferences.

a

posteriori

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Figure: A. Pontzen

Chain of 11
0.1% = 1 in 2^{10}

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Chain of 11 somewhere
within 1,000 trials

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HTTTTTHTTTTTHTTTTTHTTTTTHTTTTTHTTTTTHTTTTTHTTTTTHTTTTTHTTTTT

Figure: A. Pontzen

Chain of 11 somewhere
within 1,000 trials

$$1 - (99.9\%)^{1000} = 38\%$$

Figure: A. Pontzen

Data Analysis Pipeline: Motivation II

- Very important to perform **blind analysis** with no *a posteriori* selection effects!
 - Design pipeline with model and specific dataset in mind
 - Calibrate using instrument simulation: **null test**
 - Test sensitivity of pipeline to **simulated dataset with signal**
 - Pipeline “**frozen**” before looking at data

Data analysis pipeline

- Must reduce data volume: **target model features**
- Collision localized on the sky: **don't** want to go to harmonic space.
- Observables:
 - azimuthal symmetry
 - causal boundary (?)
 - long-wavelength modulation inside a disk
- Pipeline:
 - **wavelet analysis**: pick out significant localized features
 - **edge detection**: sensitive to causal boundary
 - **Bayesian model selection/parameter estimation**: is collision model favoured over just CMB+noise?

needlet transform (a.k.a. blob detector)

- spherical needlets have nice localization properties in both real and harmonic space
- Use three types:
 - standard spherical needlets $B=2.5$
 - standard spherical needlets $B=1.8$
 - Mexican needlets with $B=1.4$
- “Bandwidth parameter” B chosen for physics reasons (sensitivity to bubble sizes of interest)
- Calibrate variance at each pixel for a given mask with 3000 cosmic variance sims (interested in features at large scales where WMAP is CV-limited)

needlet coefficient map

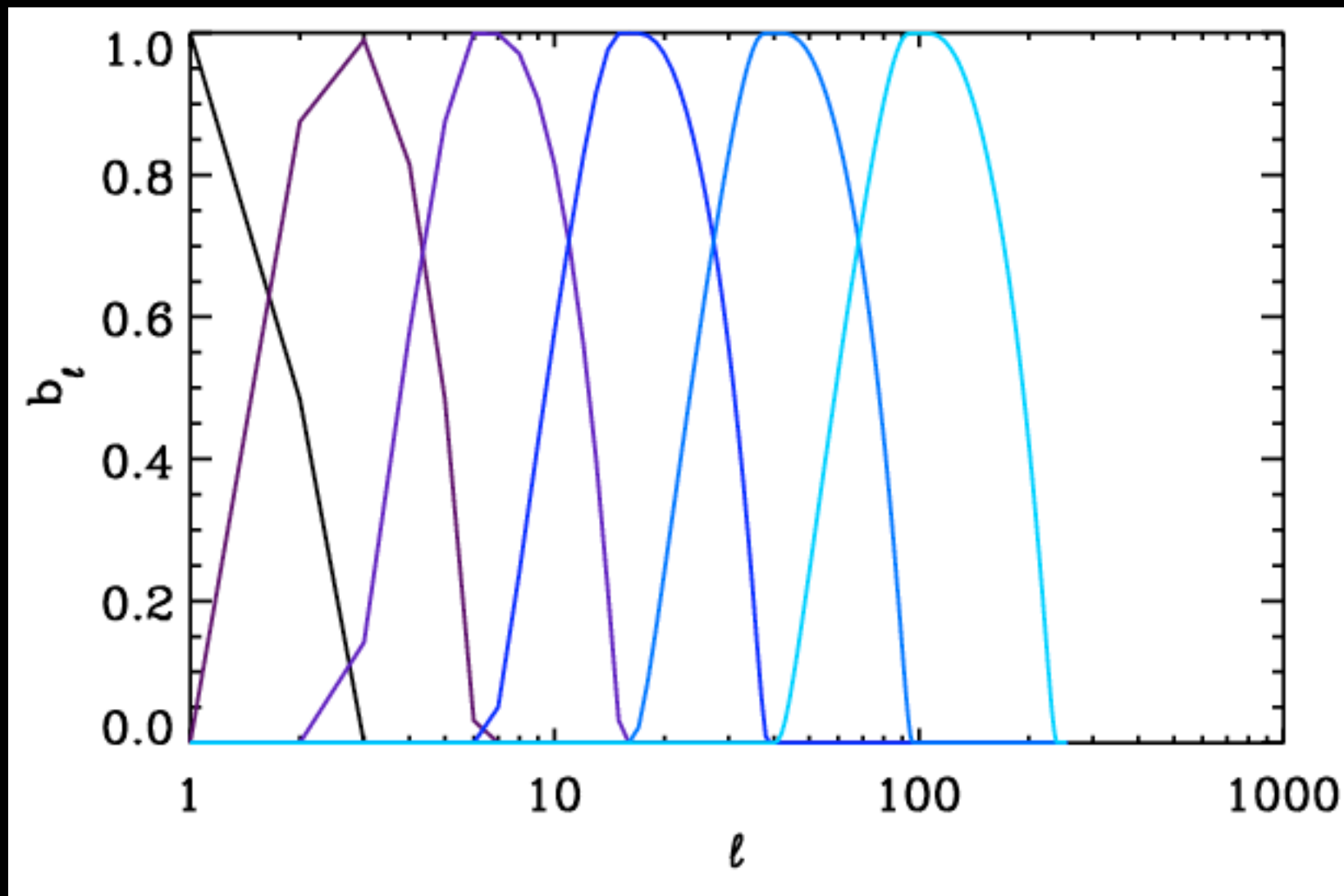
$$\beta_{jk} = \sqrt{\lambda_{jk}} \sum_{\ell} b \left(\frac{\ell}{B^j} \right) \sum_{m=-\ell}^{\ell} a_{\ell m} Y_{\ell m}(\hat{\gamma}_k)$$

B = “bandwidth”

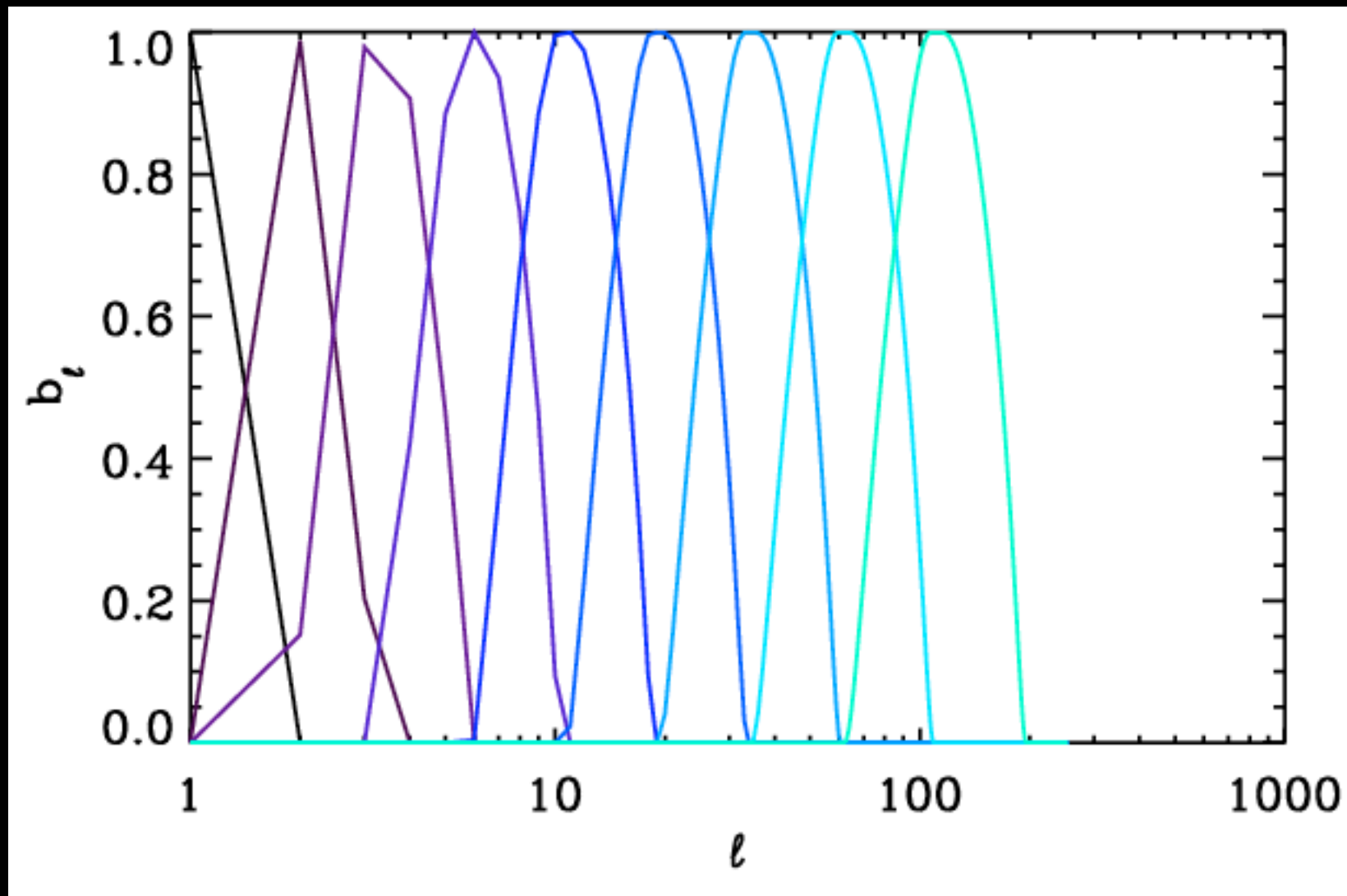
j = frequency

k = pixel

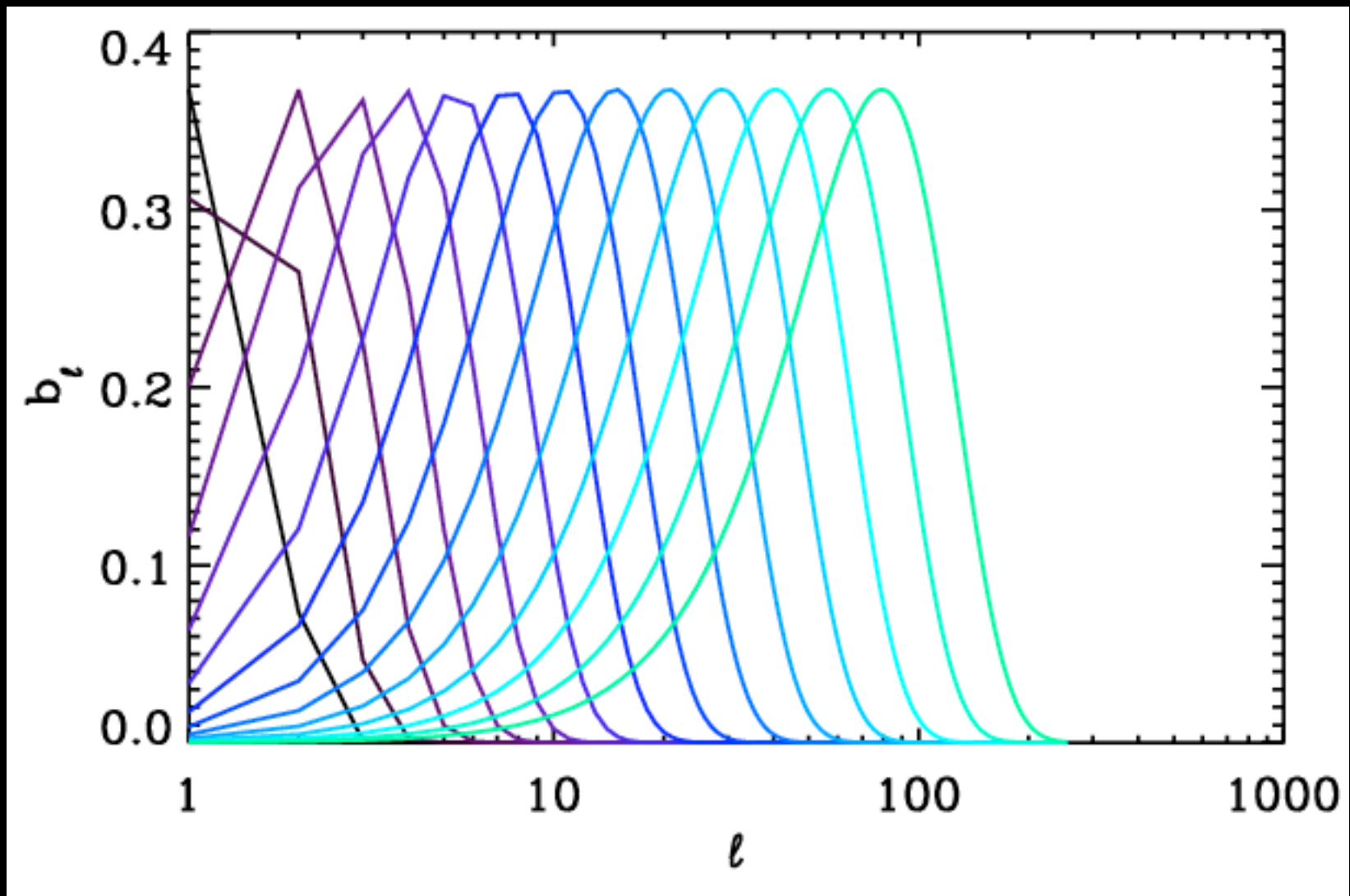
Standard needlets $B=2.5$



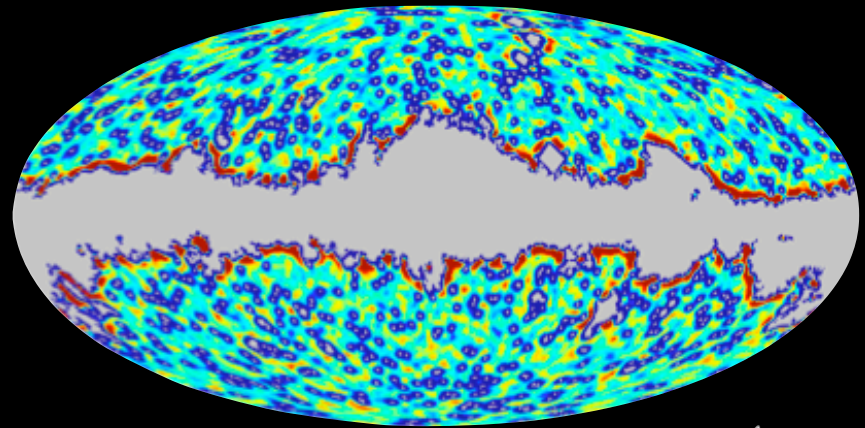
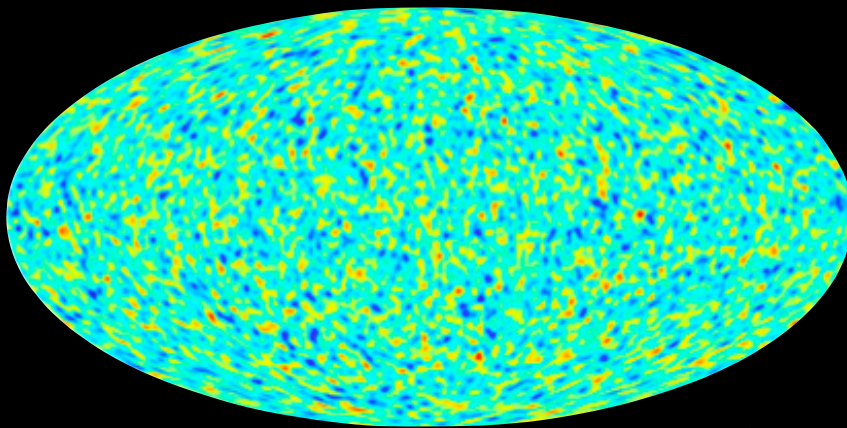
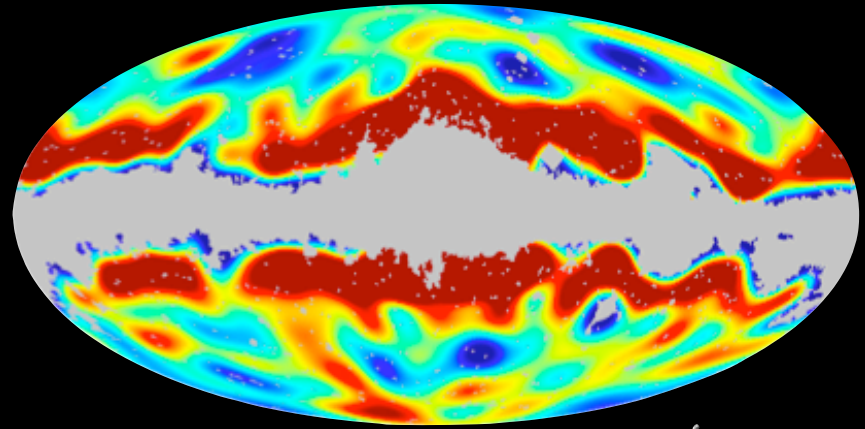
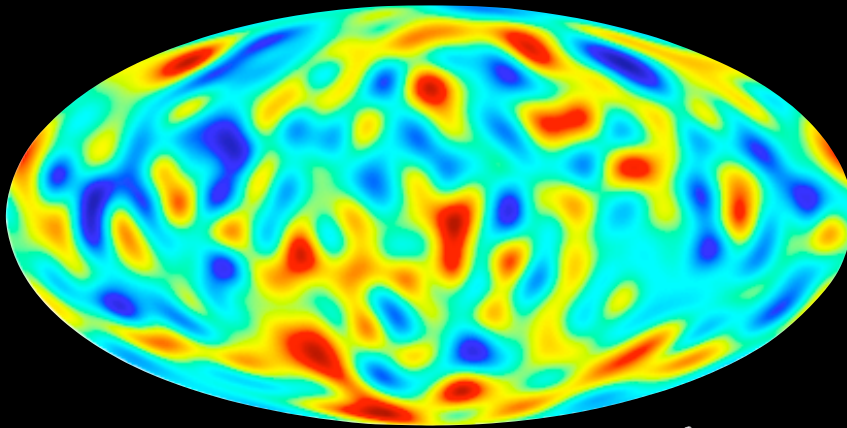
Standard needlets $B=1.8$



Mexican needlets $B=1.4$



needlet variances



Top row: standard needlets $B=2.5$, $j=2$
Bottom row: Mexican needlets $B=1.4$, $j=11$

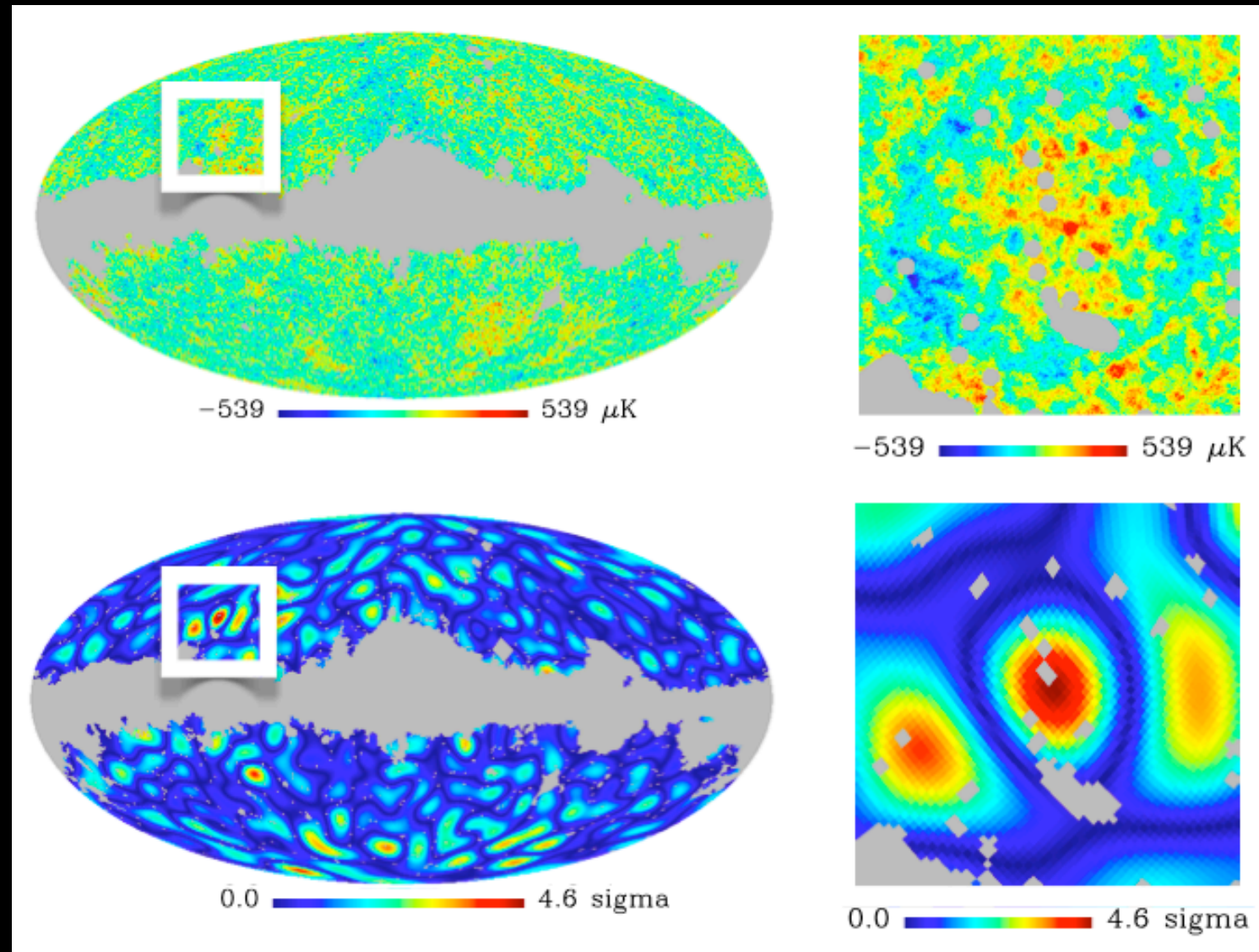
needlet significance statistic

$$S_{jk} = \frac{|\beta_{jk} - \langle \beta_{jk} \rangle_{\text{gauss, cut}}|}{\sqrt{\langle \beta_{jk}^2 \rangle_{\text{gauss, cut}}}}$$

j = frequency

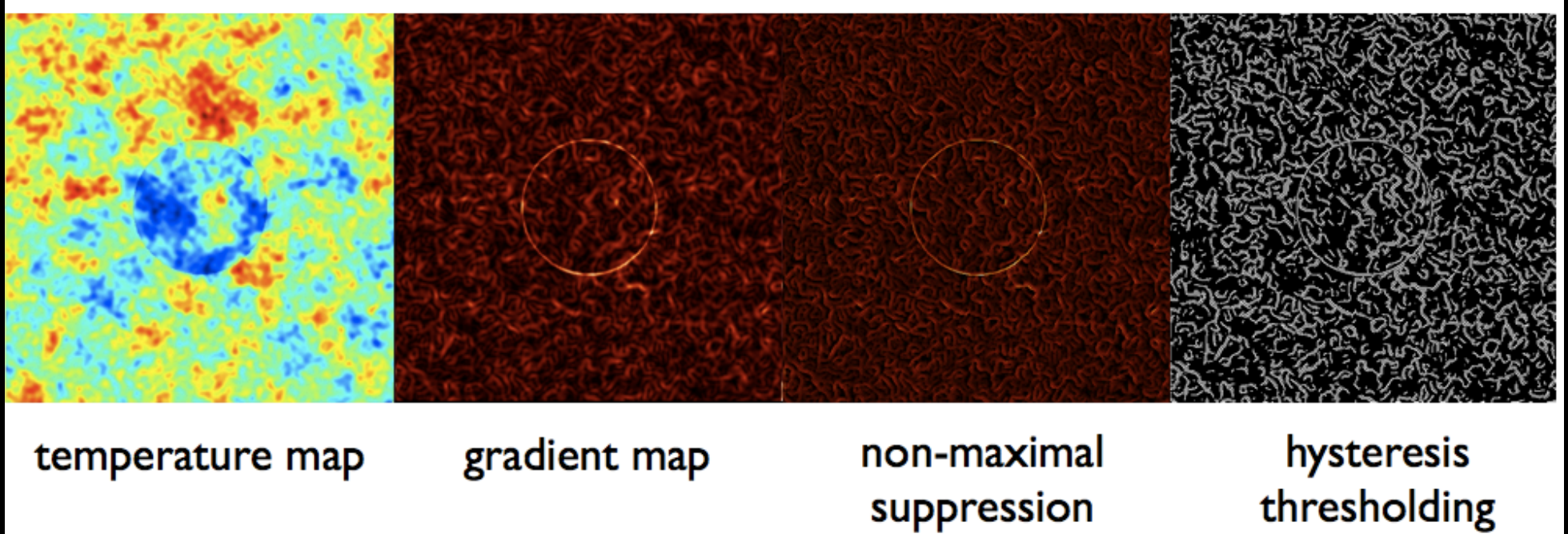
k = pixel

simulated needlet detection example



Edge detection algorithm

- Use **Canny** edge detection algorithm to search for circular edges allowed by model:
 - ▶ Generate image gradients
 - ▶ Thin into single-pixel proto-edges
 - ▶ Stitch together into “true” edges



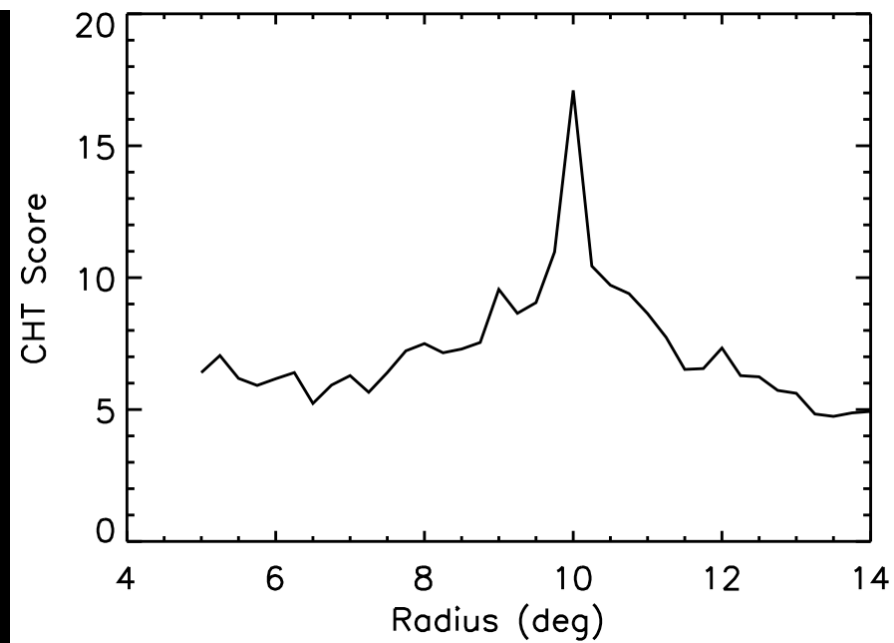
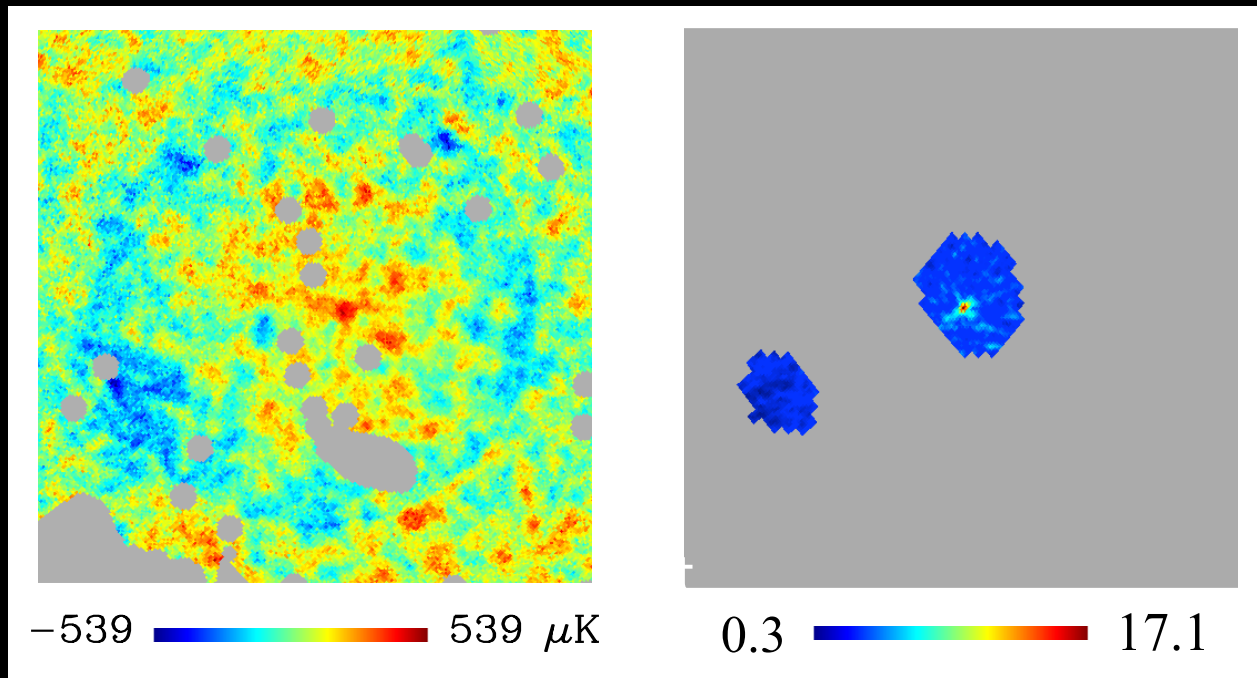
Circular Hough Transform

- Algorithm assumes each true edge pixel **lies on the edge of a circle**.
 - ▶ Scan true edge map accumulating most likely circle centres at a given radius.



Causal edge (if present) dramatically enhances observability!

simulated CHT detection example



P-values vs model selection

- Frequentist p -values quantify how discrepant a data statistic is under the “null hypothesis”
- Cannot be used to perform model selection!

$$p(A | B) \neq p(B | A)$$

100% 0.01%

A = I am a scientist

B = I am a CMB cosmologist

$$p(A | B) \neq p(B | A)$$

?? 0.01%

A = The standard model
is basically correct

B = CMB anomalies

(“some subset of the CMB data
which we don’t like the look of”)

Reminder: parameter estimation vs model selection

The diagram illustrates the components of the Bayesian formula for parameter estimation. It features three boxes at the top: 'posterior: probability of the model given the data' (green text), 'probability of the data given the model' (orange text), and 'prior probability' (cyan text). Arrows point from these boxes to the corresponding terms in the equation below. The equation is
$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{\int P(D|\theta)P(\theta)d\theta}$$
. A box labeled 'Evidence: normalizing factor' has an arrow pointing to the denominator of the equation.

posterior: probability of the model given the data

probability of the data given the model

prior probability

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{\int P(D|\theta)P(\theta)d\theta}$$

Evidence: normalizing factor

Evidence: model-averaged likelihood

Exact (pixel) likelihood includes CMB, spatially varying noise, Gaussian beam

Which model better describes the data?

$$\rho = \frac{p(M_b | D)}{p(M_0 | D)} = \frac{p(M_b)}{p(M_0)} \frac{Z_b}{Z_0} \quad \text{evidence ratio}$$

D = data highlighted by needlets

M_0 = CMB + instrument effects

M_b = bubble collision model

↑
prior model
probability ratio
(assumed to be 1)

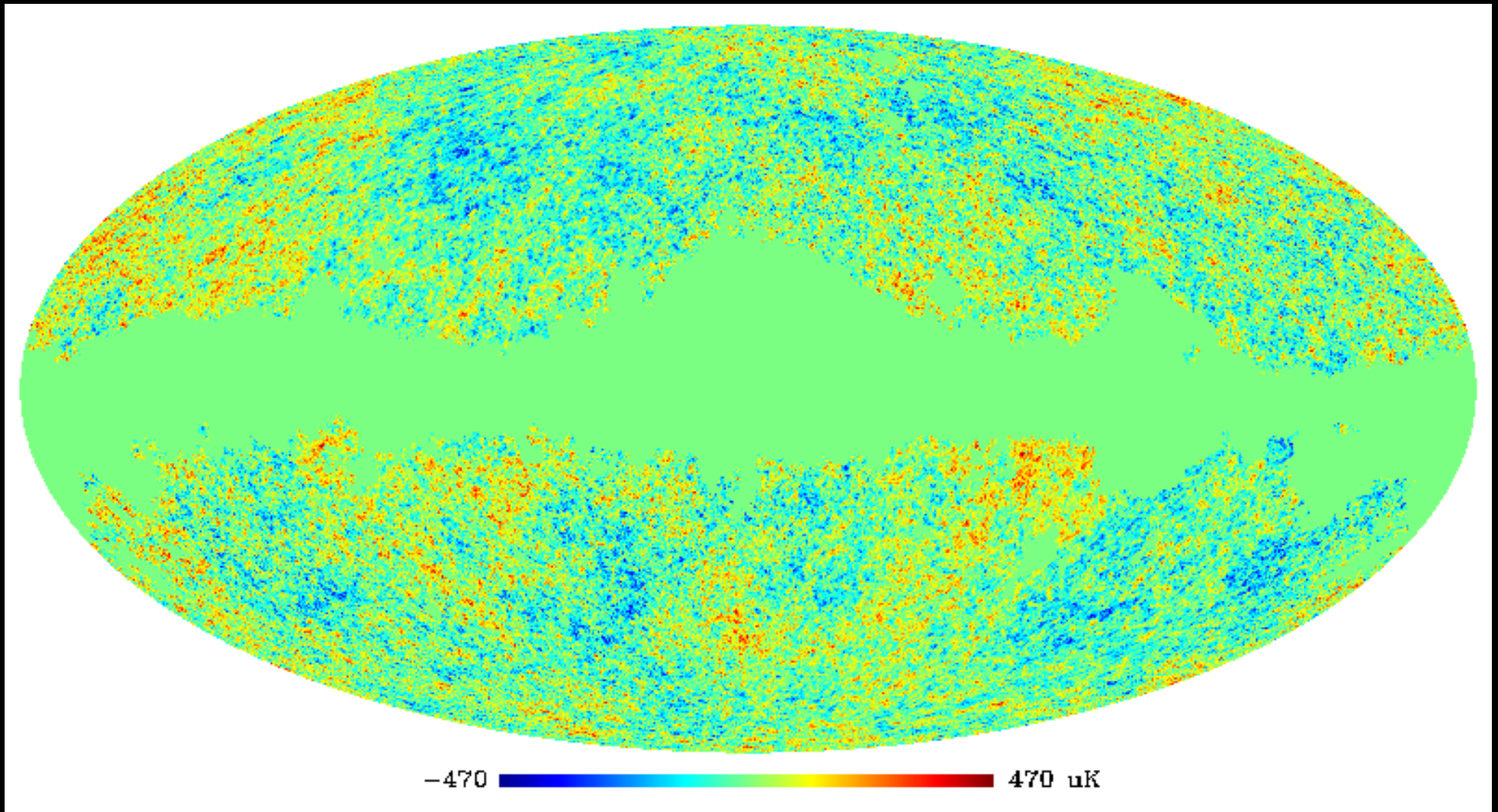
- Calculated using Multinest
- Computationally limited to < 11 deg patches (covmat inversion)
- model priors automatically set

Bayesian step examples

simulated model	$\ln \rho$
large central amplitude, strong edge	130
small central amplitude, strong edge	150
large central amplitude, weak edge	36
weak central amplitude, medium edge	5
small central amplitude, weak edge	3

Edge aids greatly in detection

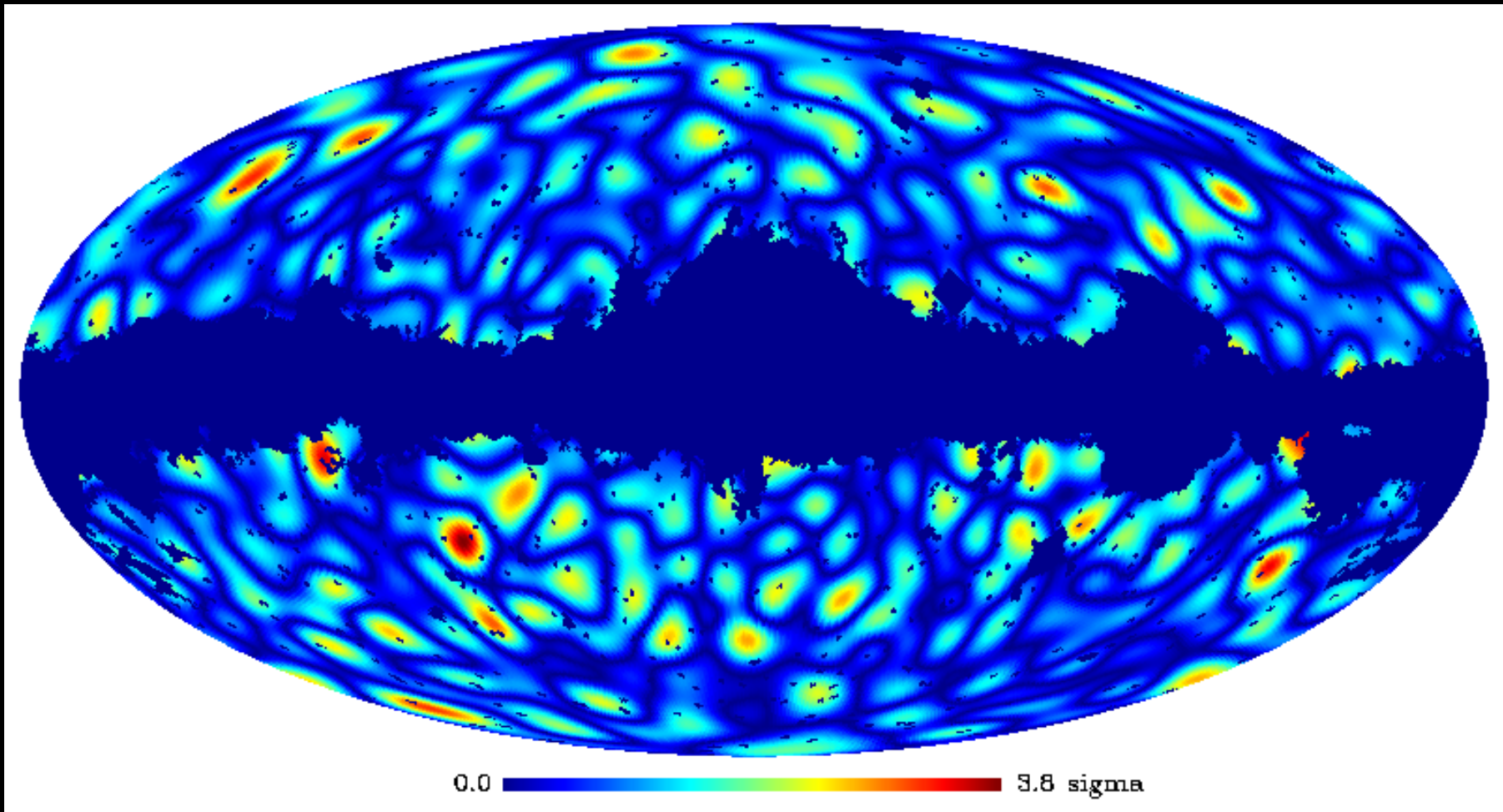
Systematics calibration simulation



WMAP7 W band end-to-end sim: starting from time stream, diffuse and point source foregrounds, realistic instrumental effects

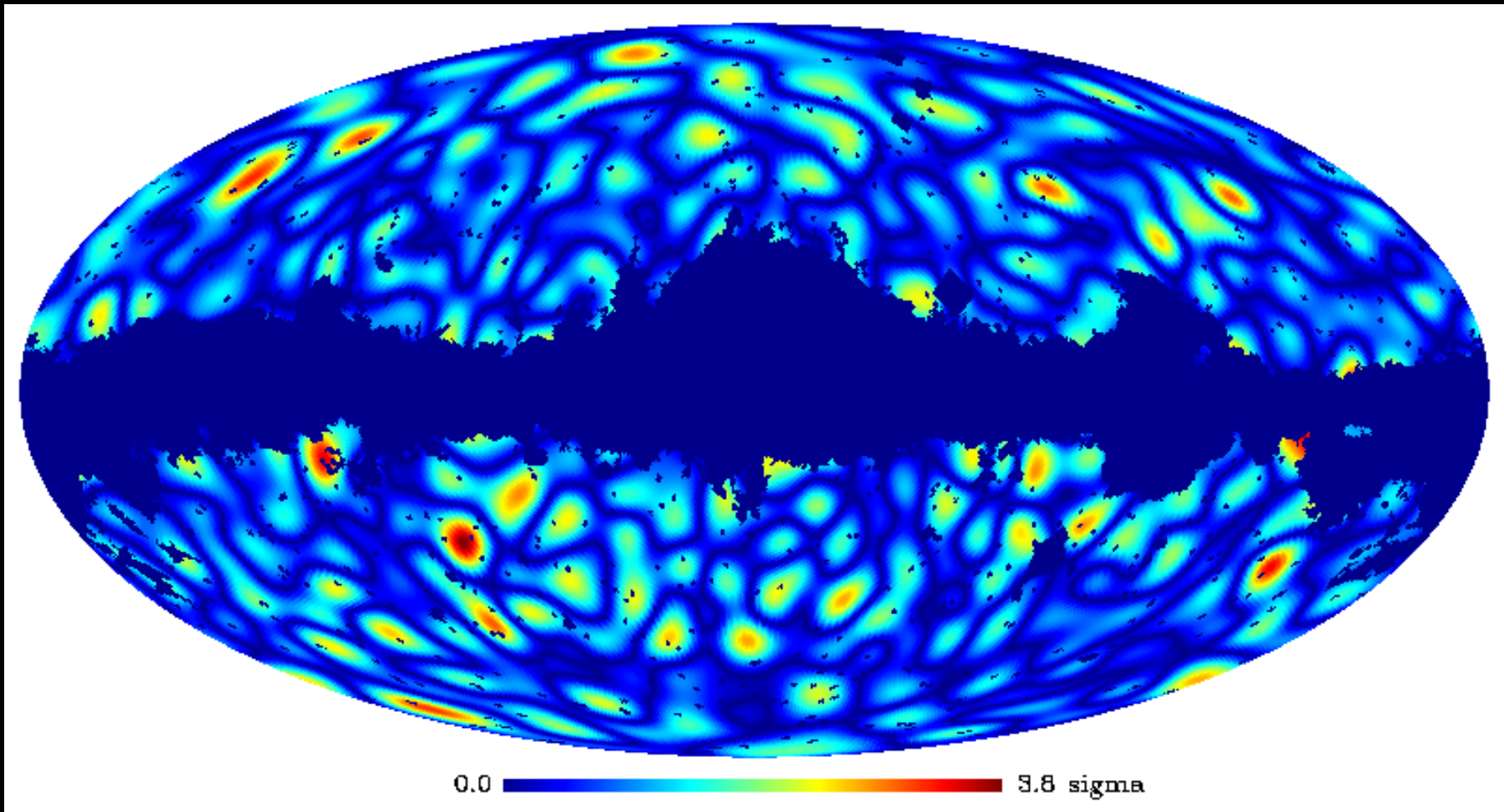
e2e simulation: needlet responses

WMAP7 W band sim example: std needlet 2.5 $j=3$



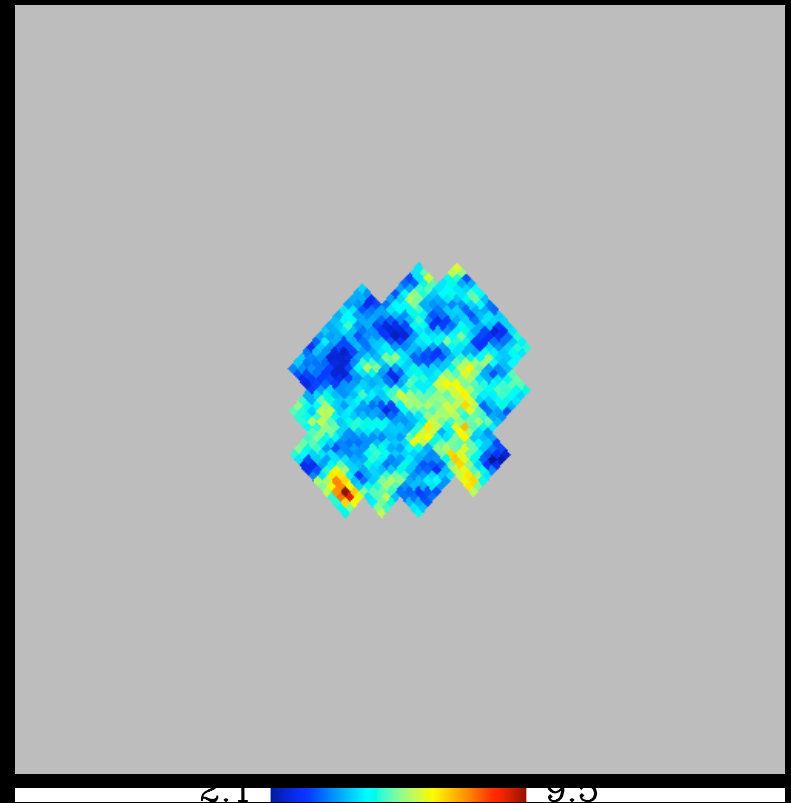
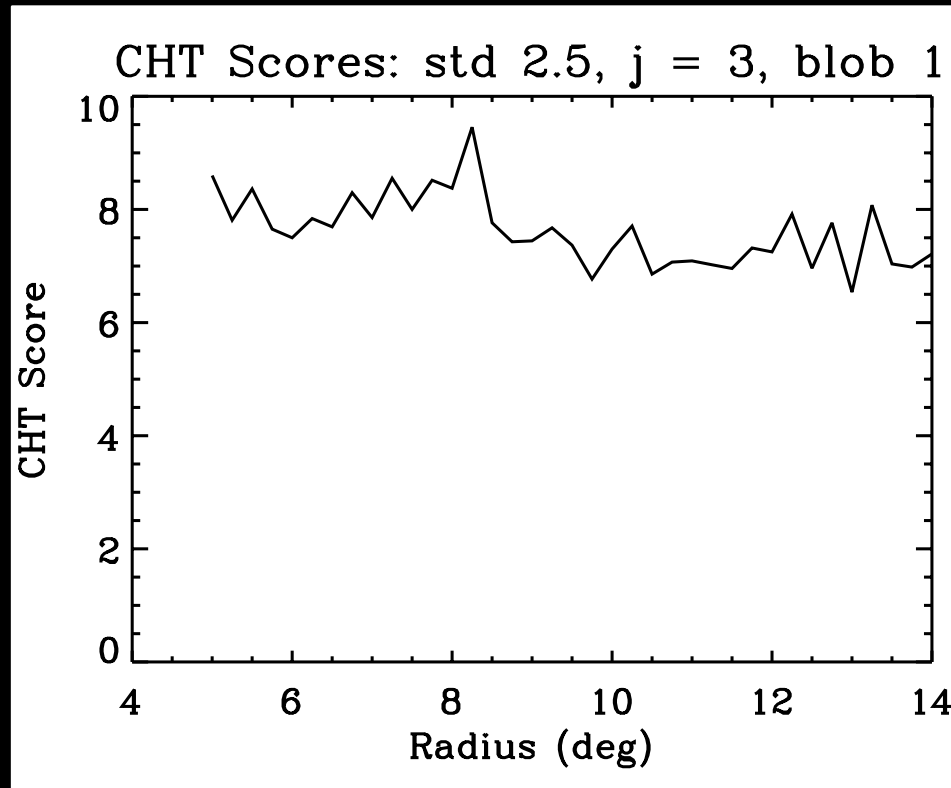
significances (sensitive to 5 - 14 degrees)

e2e simulation: needlet responses



Set thresholds such that 10 features pass: trying to discover **rare, weak features**, but later pipeline steps are computationally heavy

e2e simulation: CHT responses



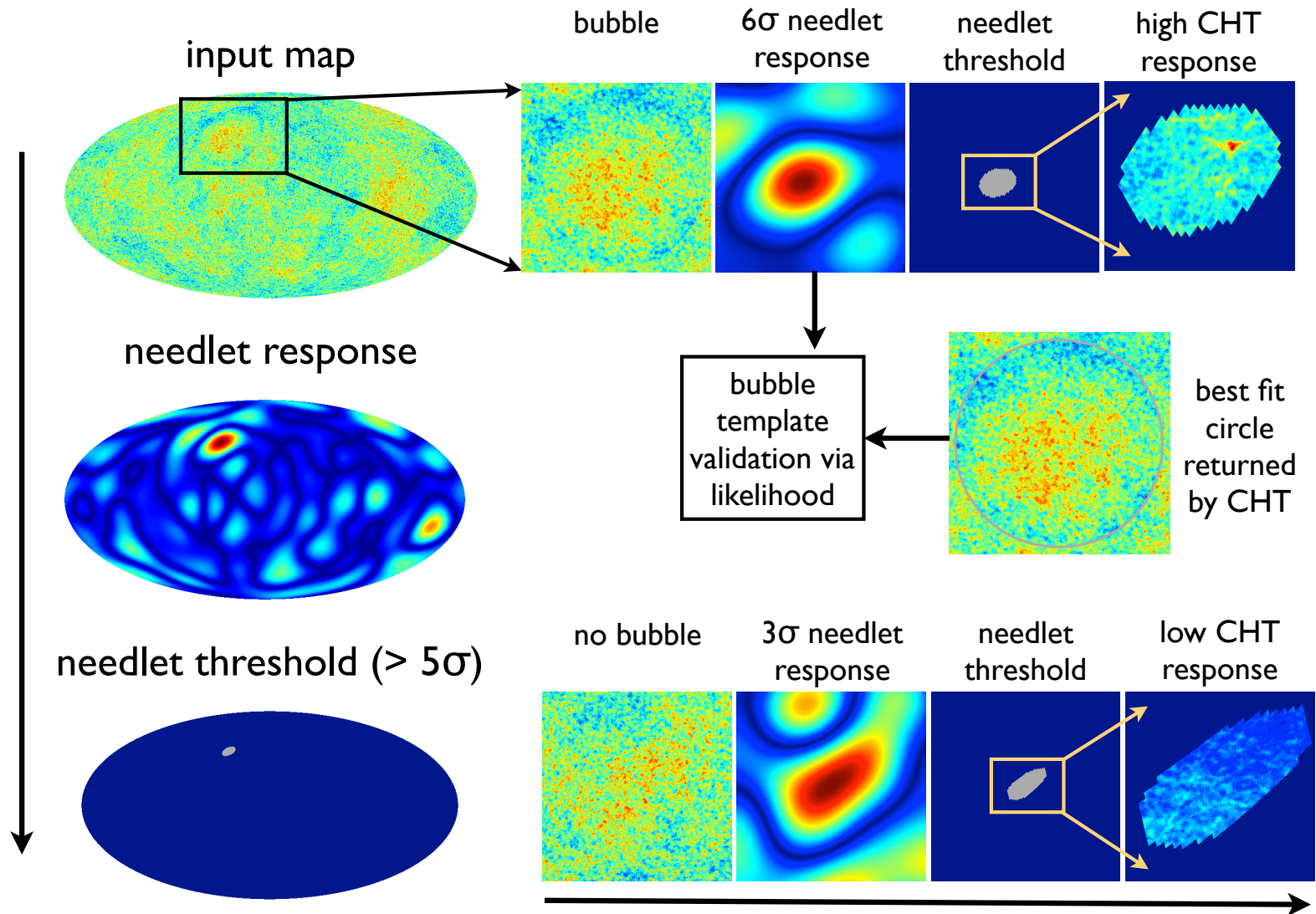
- “peakiest” CHT response found in e2e sim is small: no false detections
- confirms strong CHT peak is a “smoking gun”

e2e simulation: Bayesian analysis

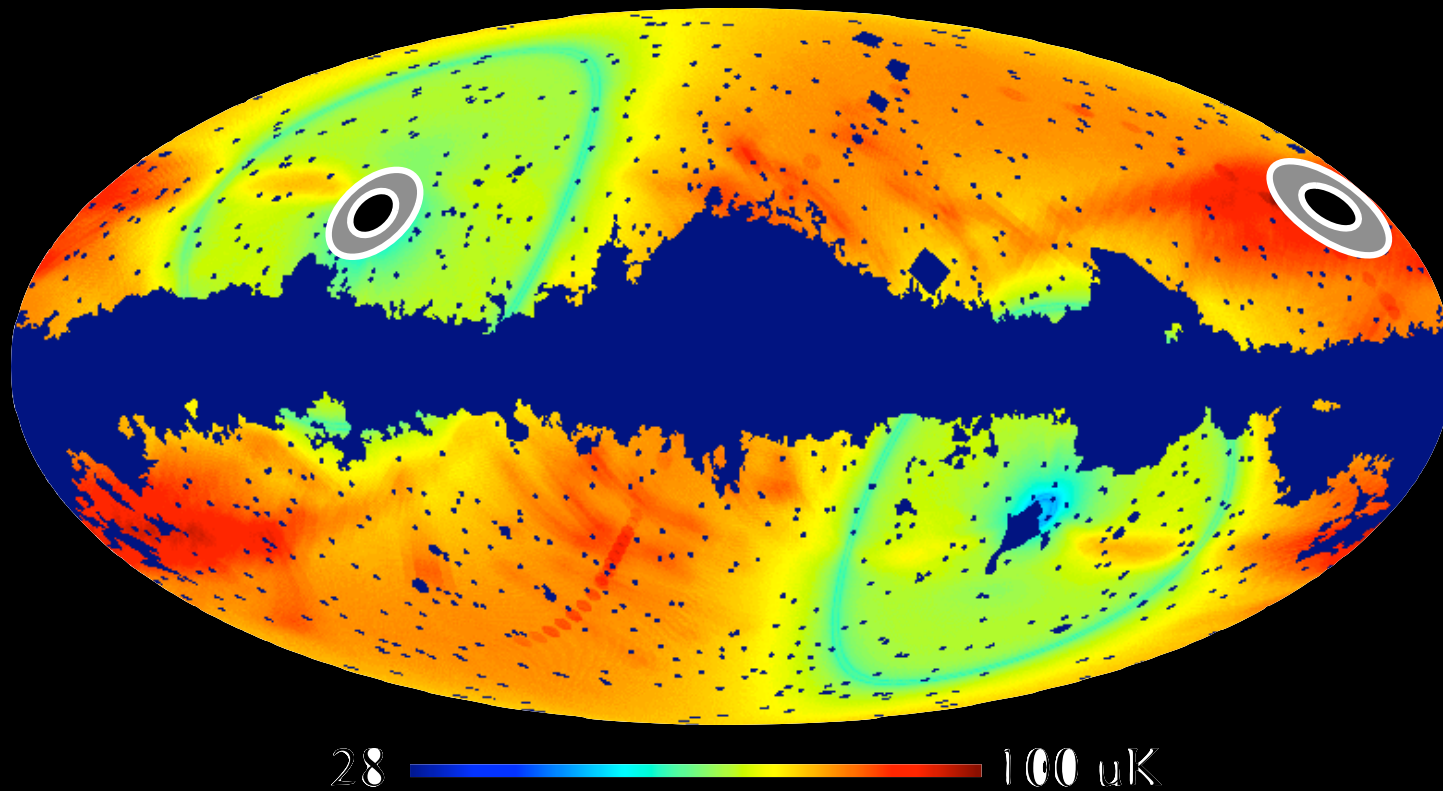
- Most “false detections” with size > 3 degrees passing the needlet threshold have very small evidence.
- For conclusive detection, require significantly exceeding threshold set by largest evidence for a “false detection” at these angular scales.

pipeline summary

bubble collision detection pipeline

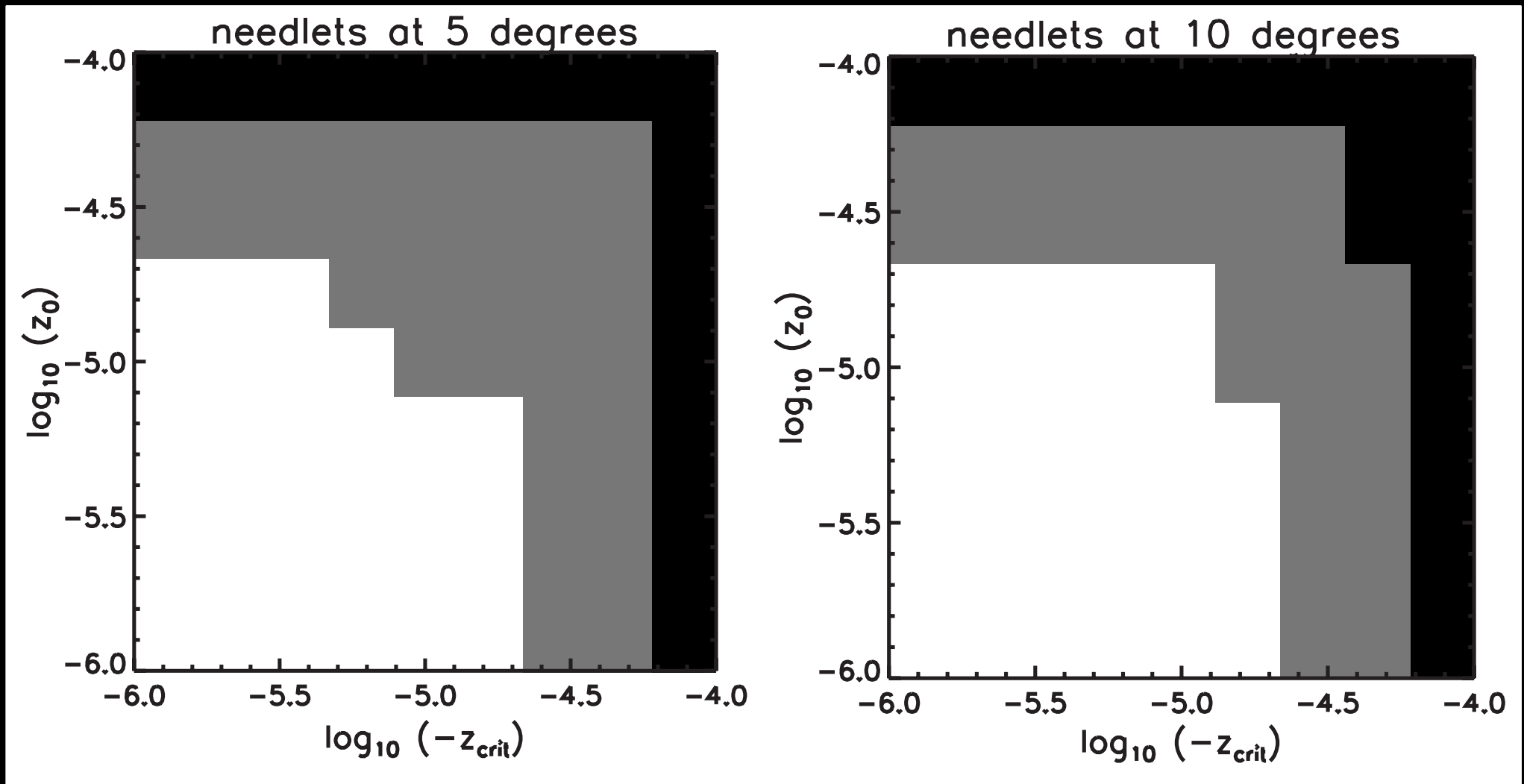


Sensitivity simulations



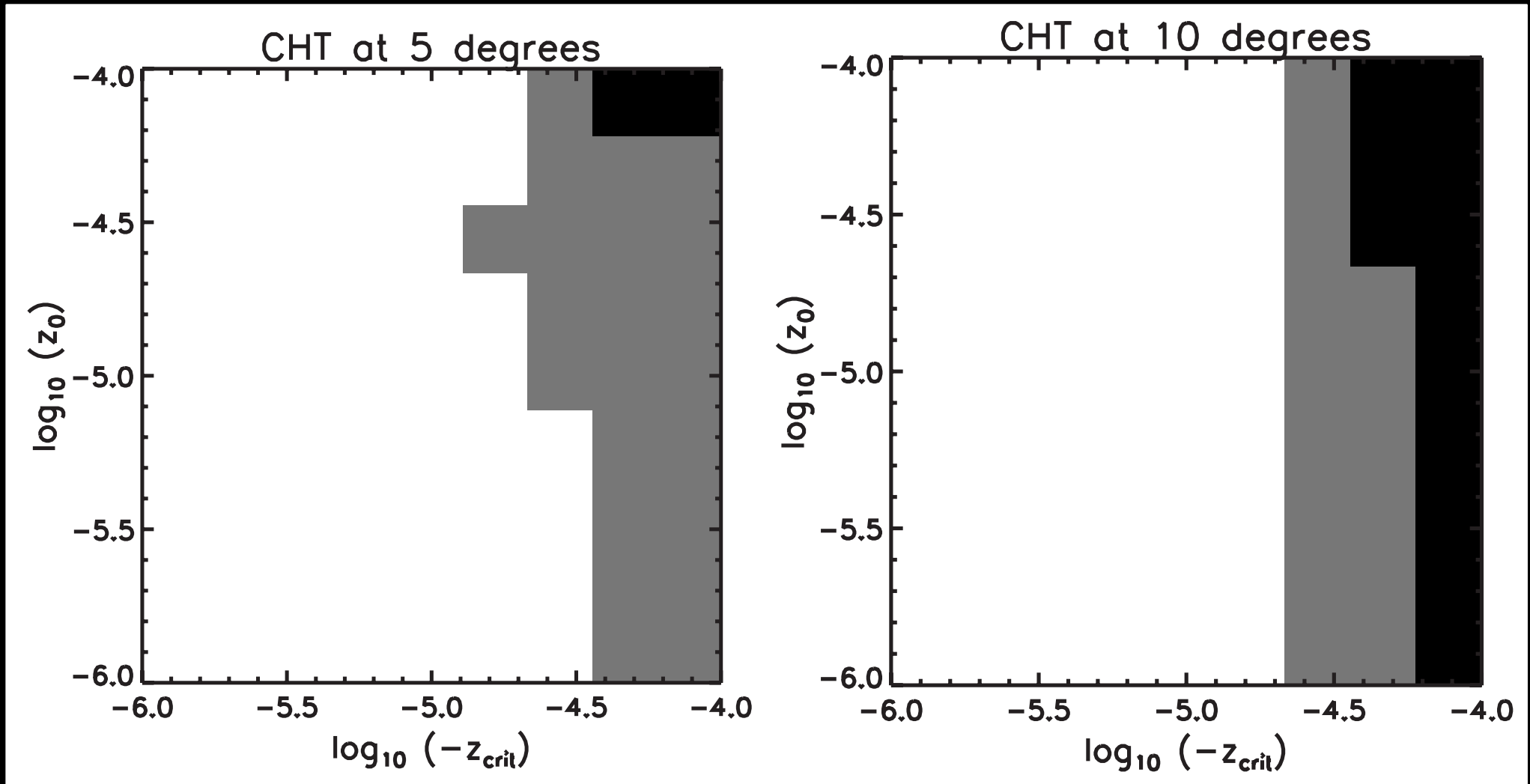
210 CMB+spatially varying noise+beam simulations of 5, 10, 25 degree collisions, sampling 35 representative parameter combinations with 3 CMB realizations each, placed at high/low noise locations

needlet sensitivity/exclusion region



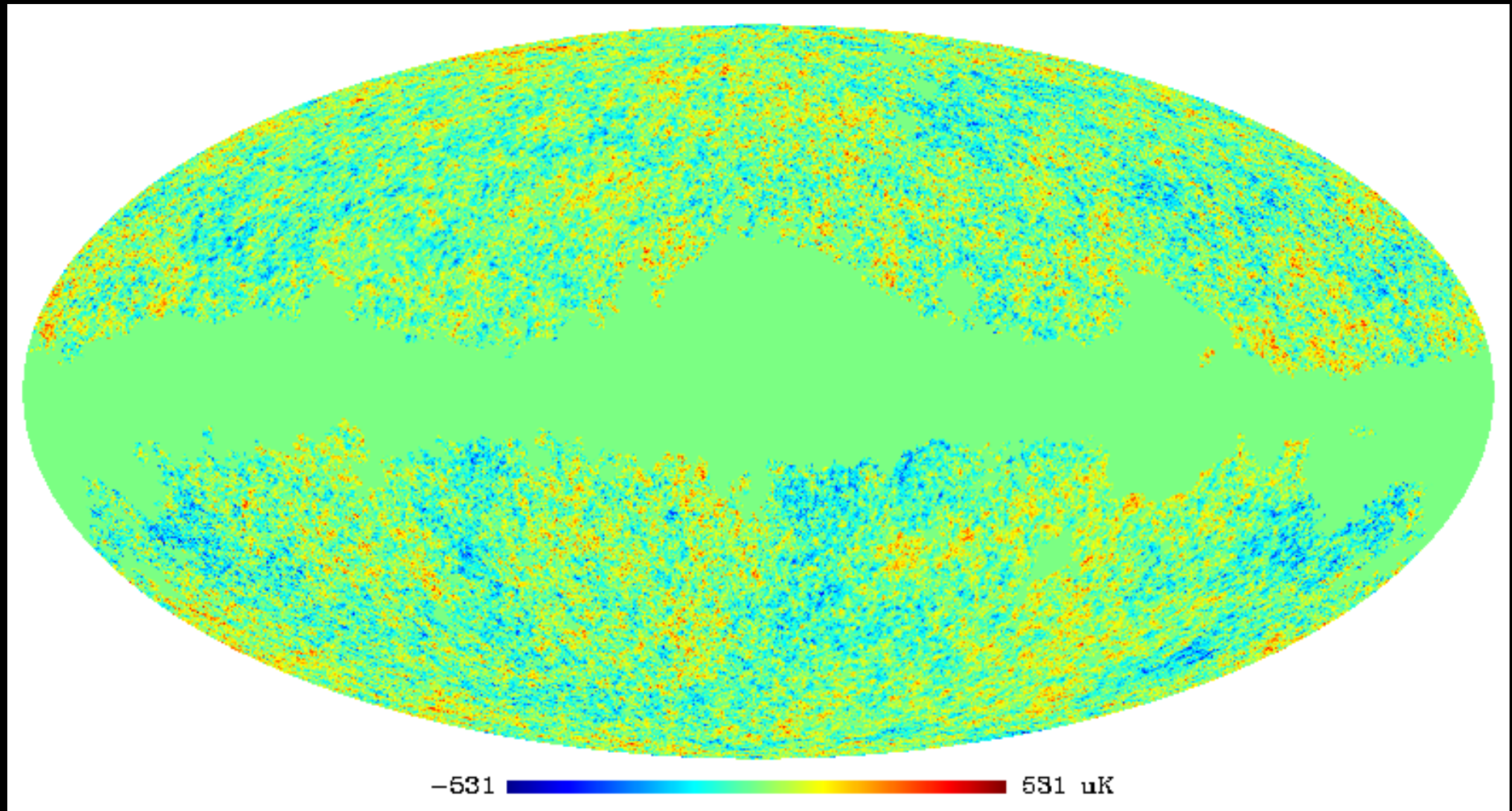
- Bayesian step would detect anything in needlet exclusion region; sensitive to needlet sensitivity region.

CHT sensitivity/exclusion region



- Limited by 1 degree CMB “realization noise” as well as experimental sensitivity/resolution.

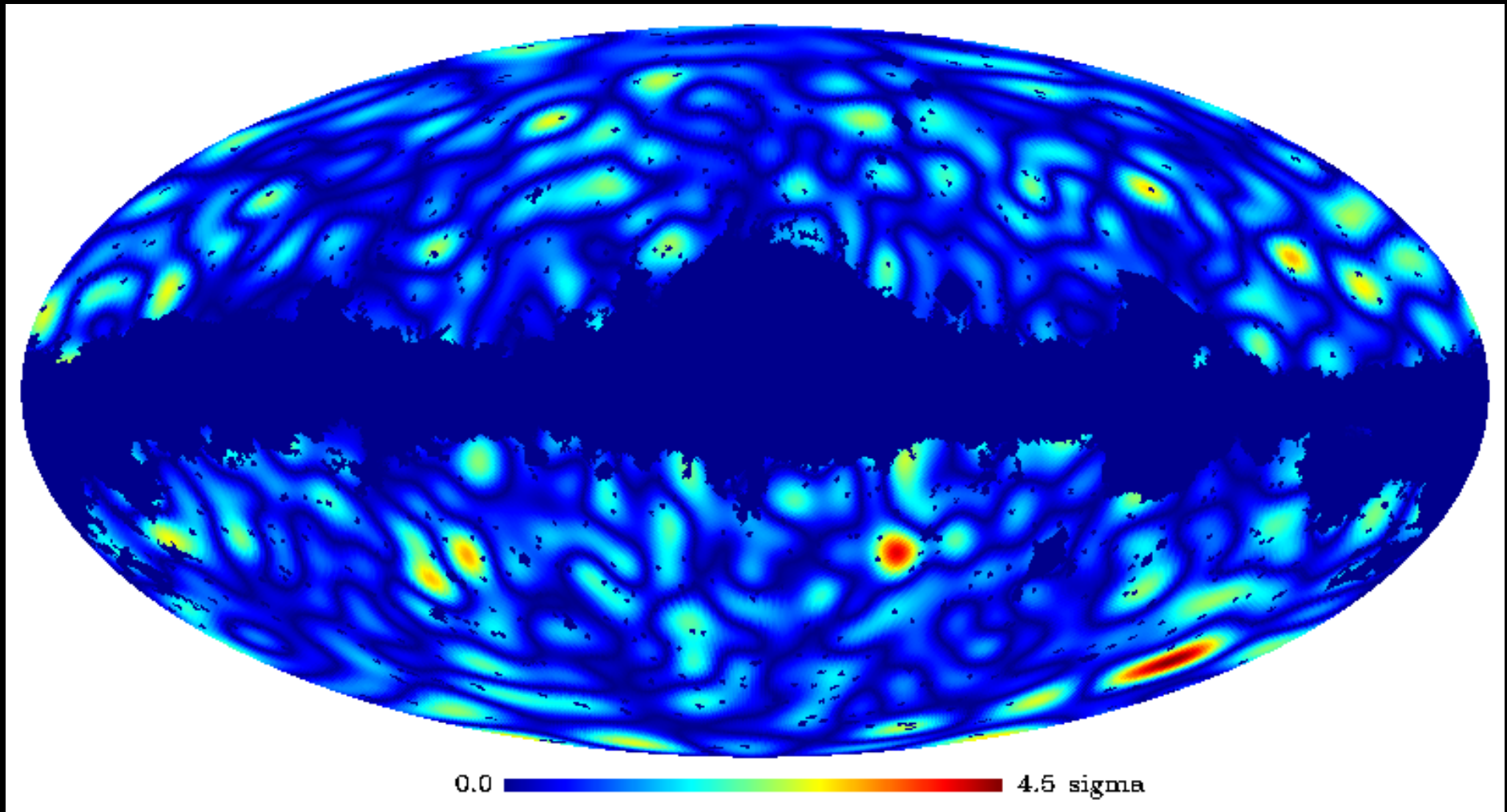
WMAP7 W band (94 GHz)



Highest resolution WMAP channel (beam 0.22 deg)

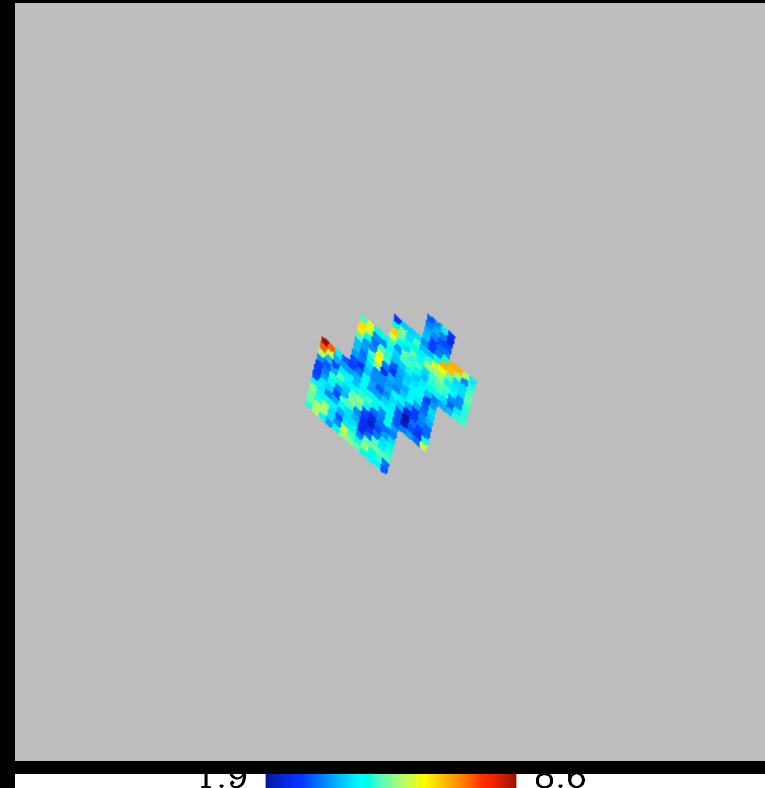
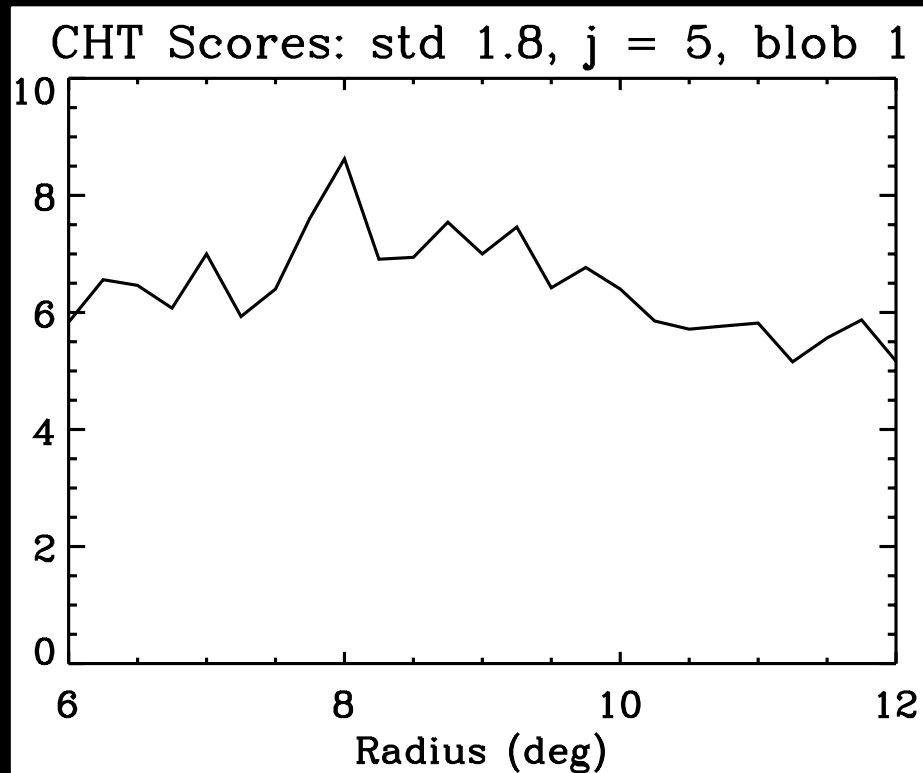
WMAP7 W band example: std needlet 2.5 $j=3$

significances (sensitive to 5 - 14 degrees)



11 features pass thresholds, with detections
in multiple needlet types/frequencies

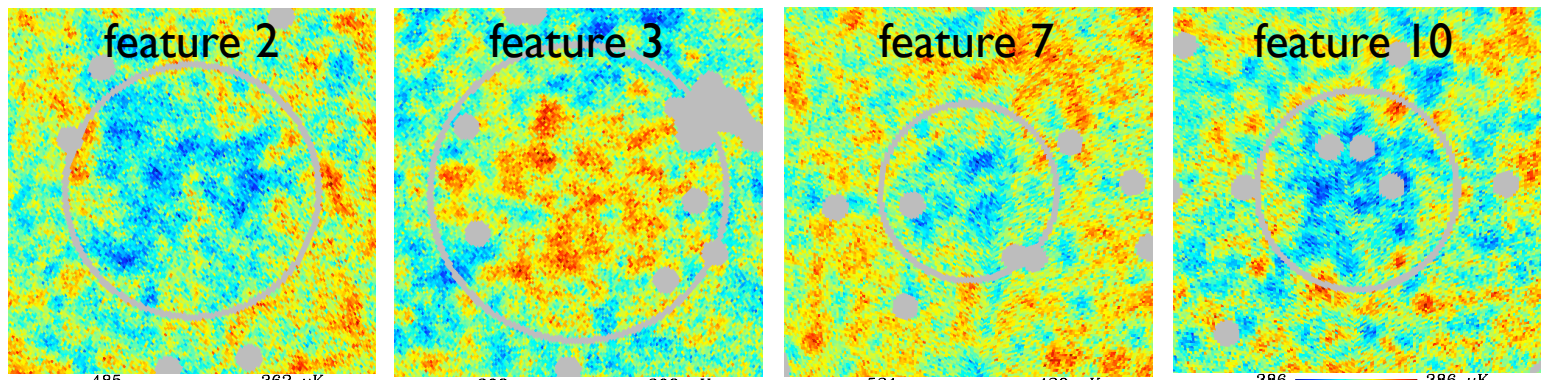
WMAP7 W band: CHT response



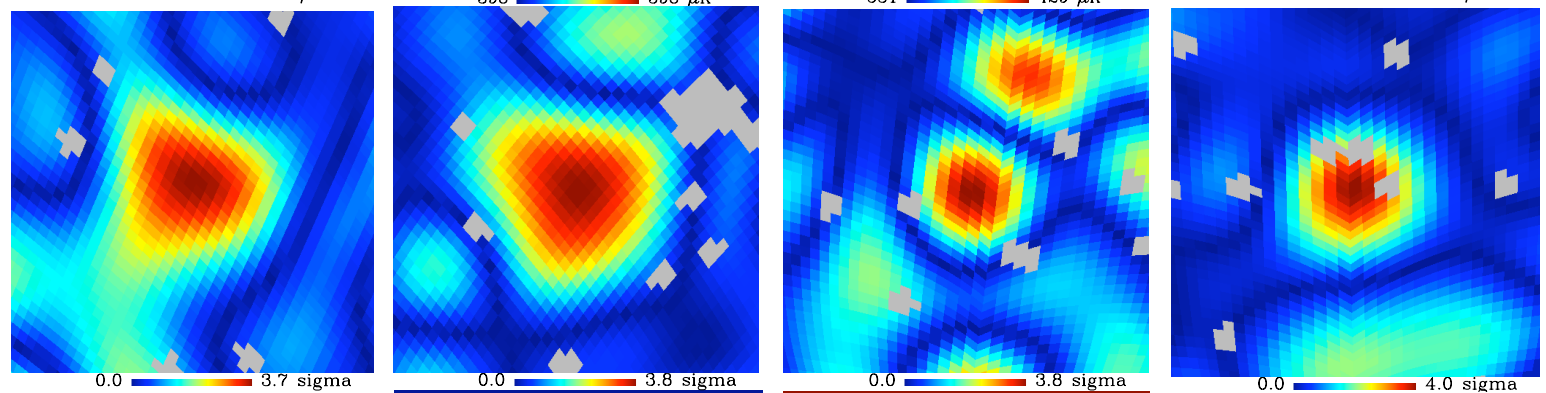
- “peakiest” CHT response found in W band data
- no circular temperature discontinuities detected
- no conclusive detection can be claimed

Bayesian model selection

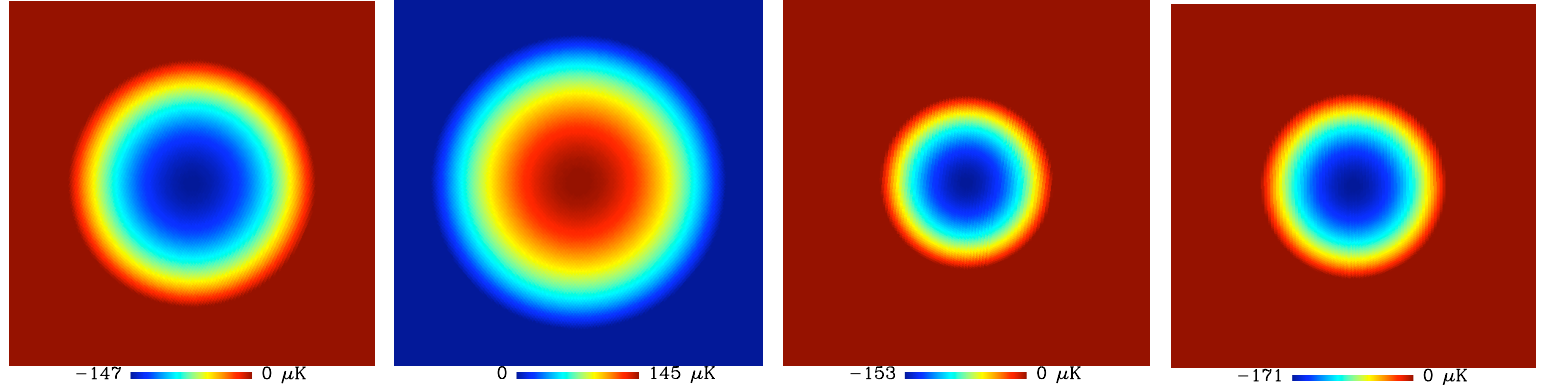
- Find **four** features with no detectable temperature discontinuity (at WMAP quality data) but with evidence ratios **significantly higher** than false detection threshold evidence ratio.
- Evidence ratios **consistent** with simulated collisions using marginalized parameters.
- **Cannot** claim a conclusive detection.
- All four features are at about our angular size CHT detection threshold of 5 deg, and within the needlet sensitivity region.



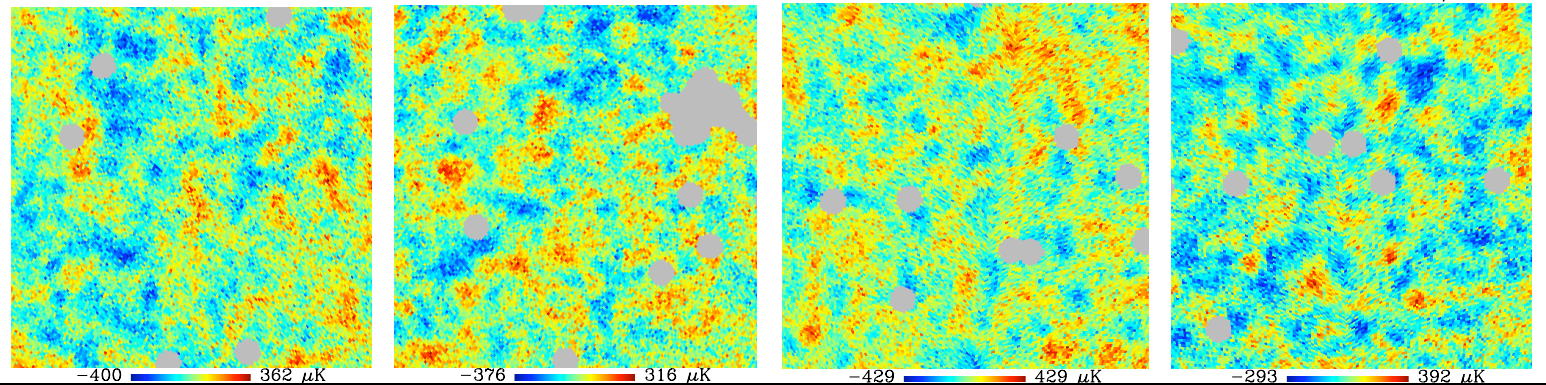
data



needlet
significance

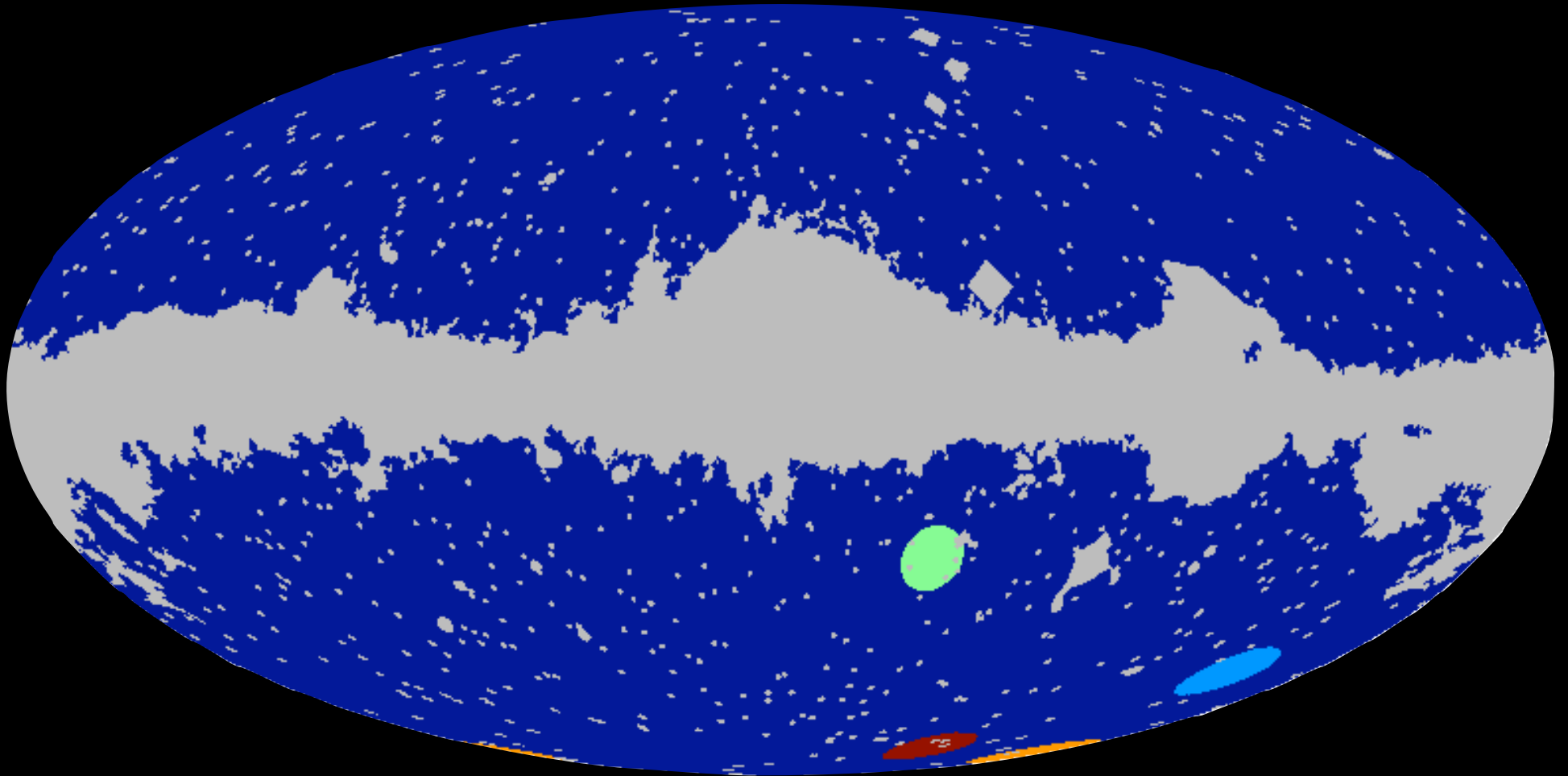


template

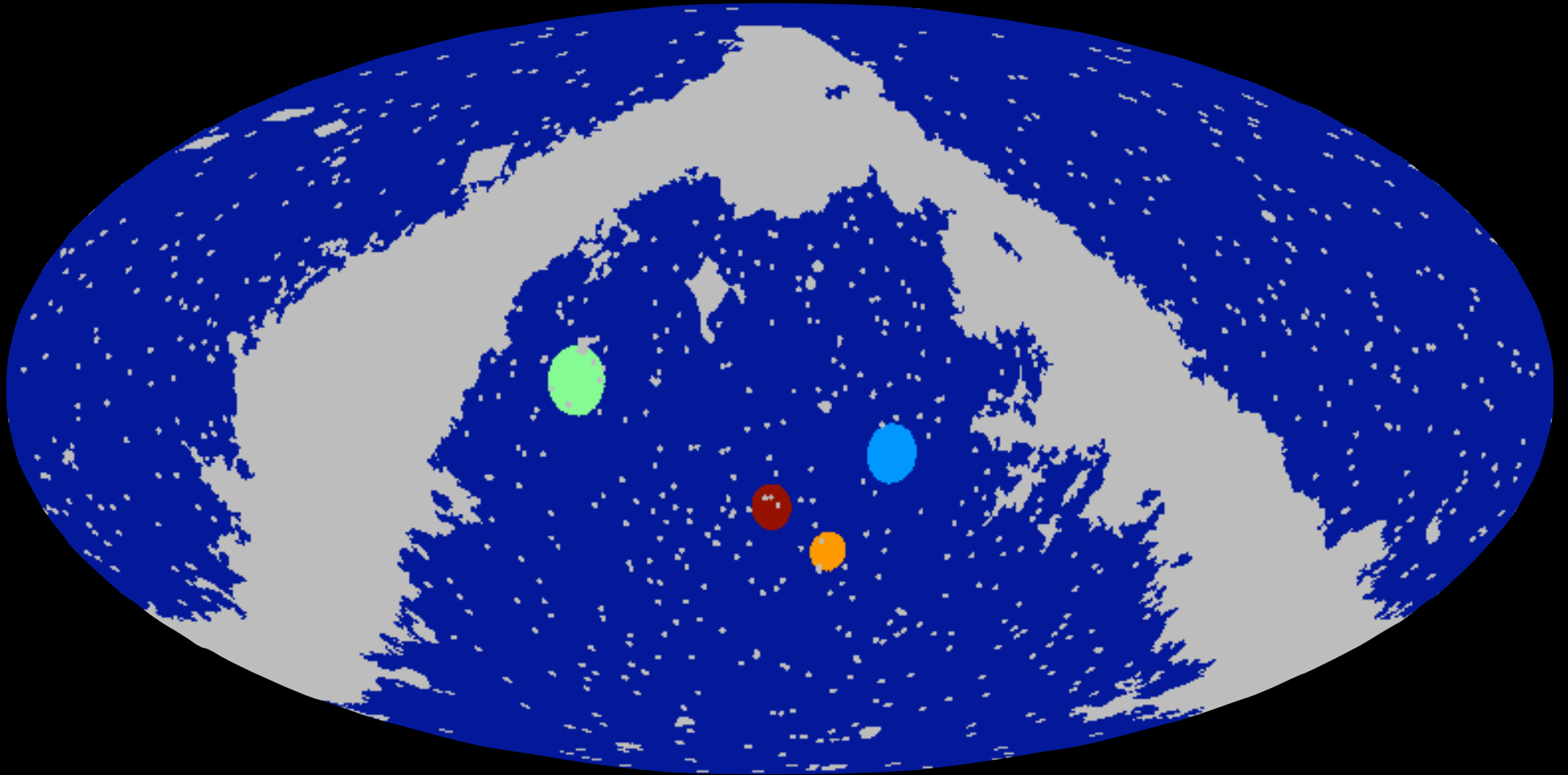


data minus
template

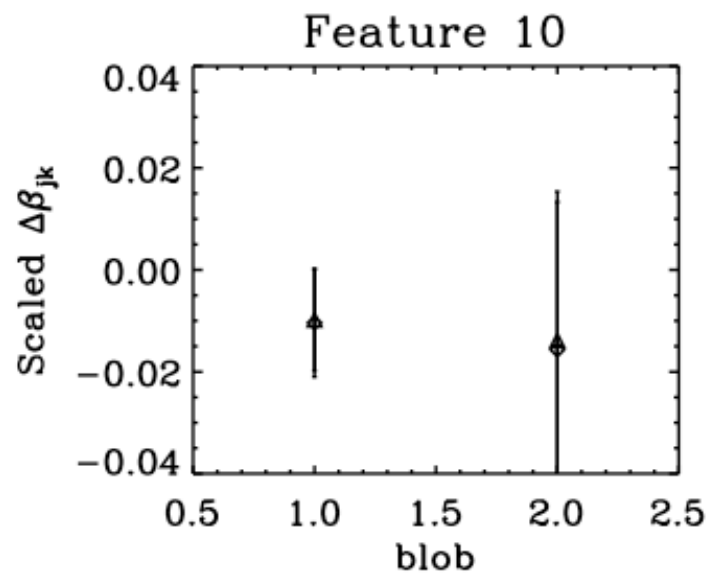
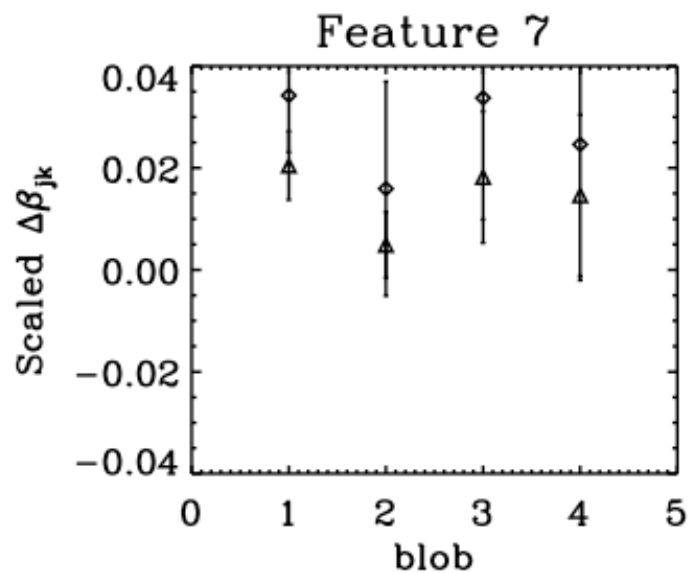
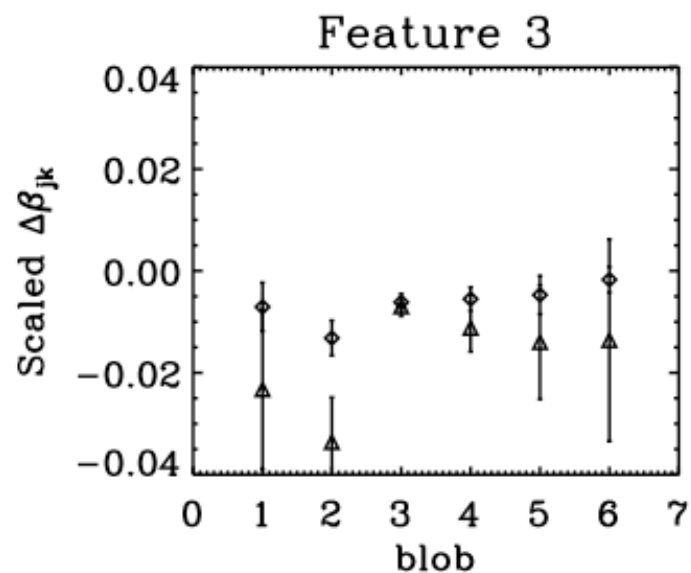
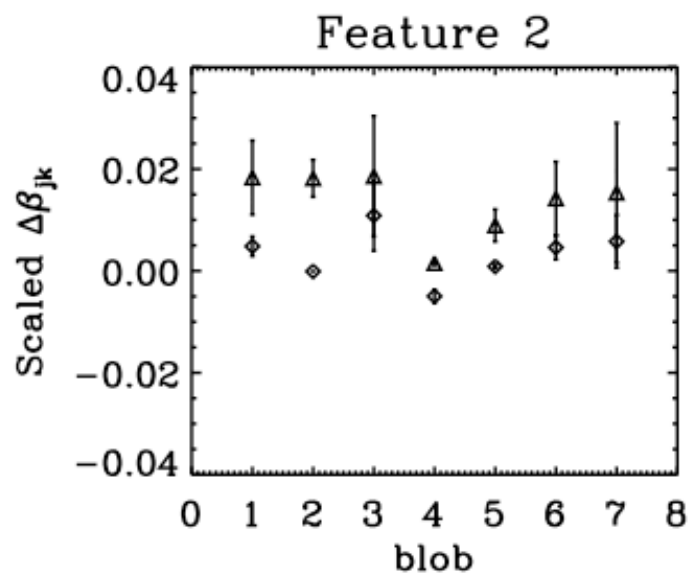
feature locations - Galactic coords



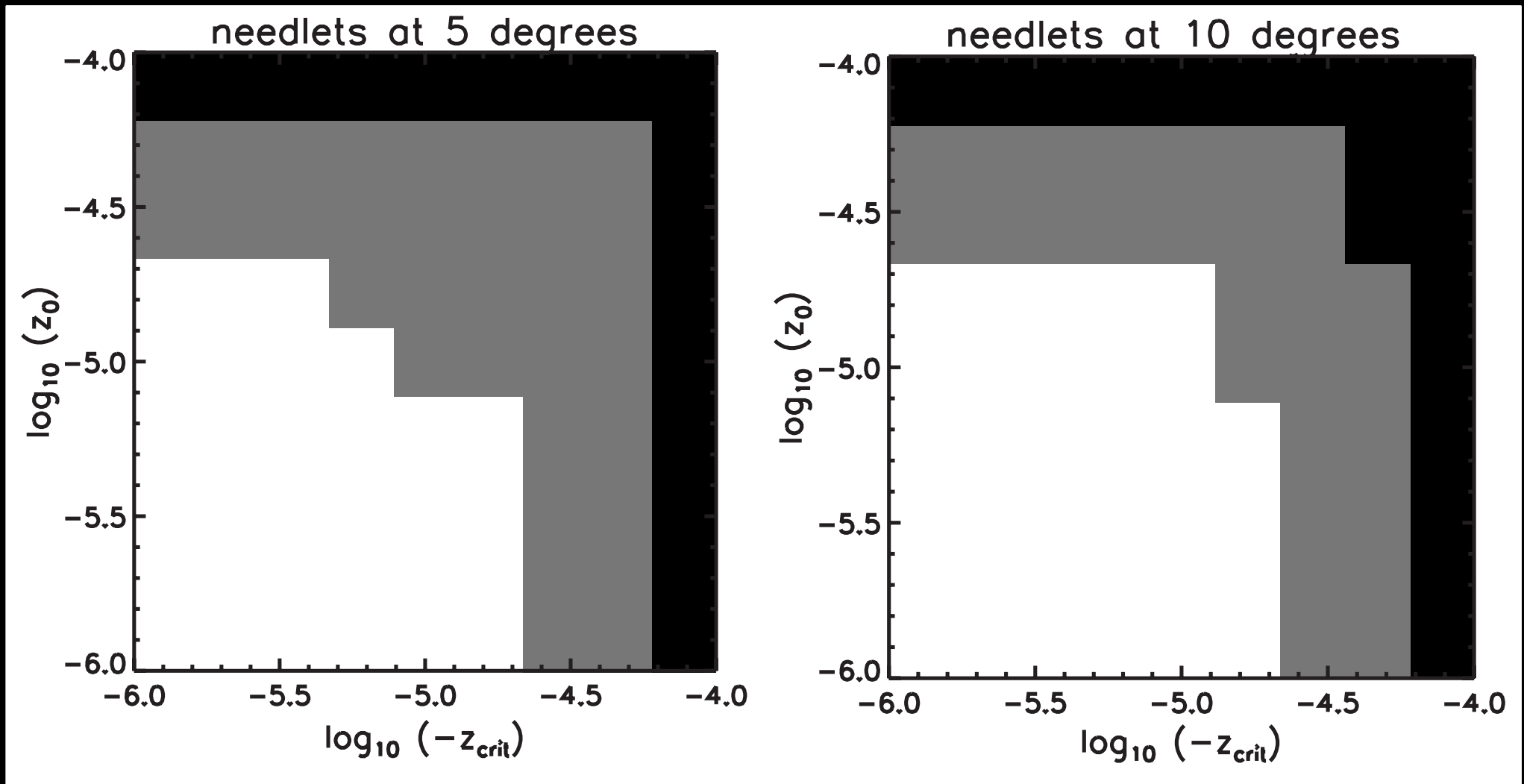
feature locations - rotated



Checking for foreground residuals

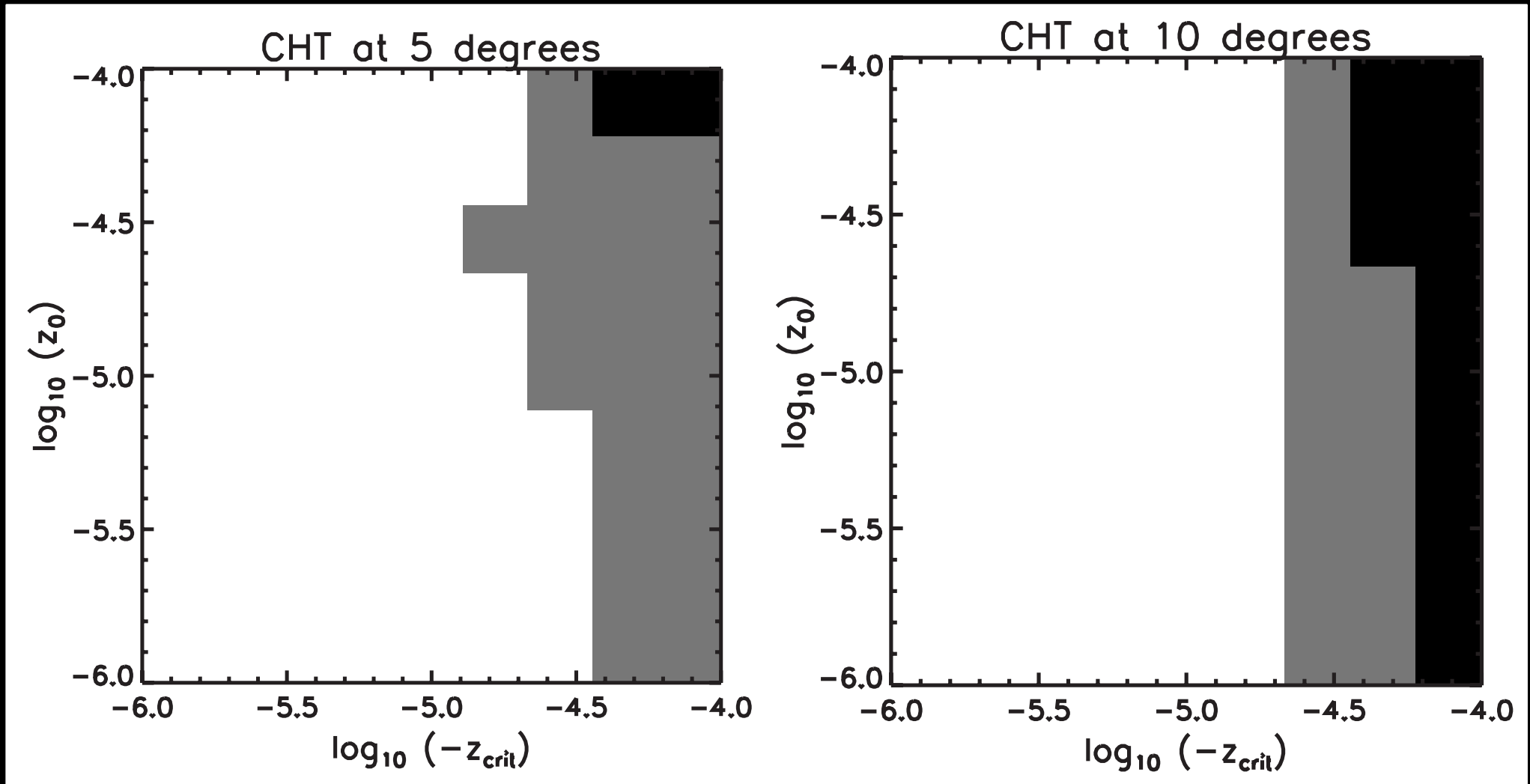


needlet sensitivity/exclusion region



- Bayesian step would detect anything in needlet exclusion region; sensitive to needlet sensitivity region.

CHT sensitivity/exclusion region



- Limited by 1 degree CMB “realization noise” as well as experimental sensitivity/resolution.

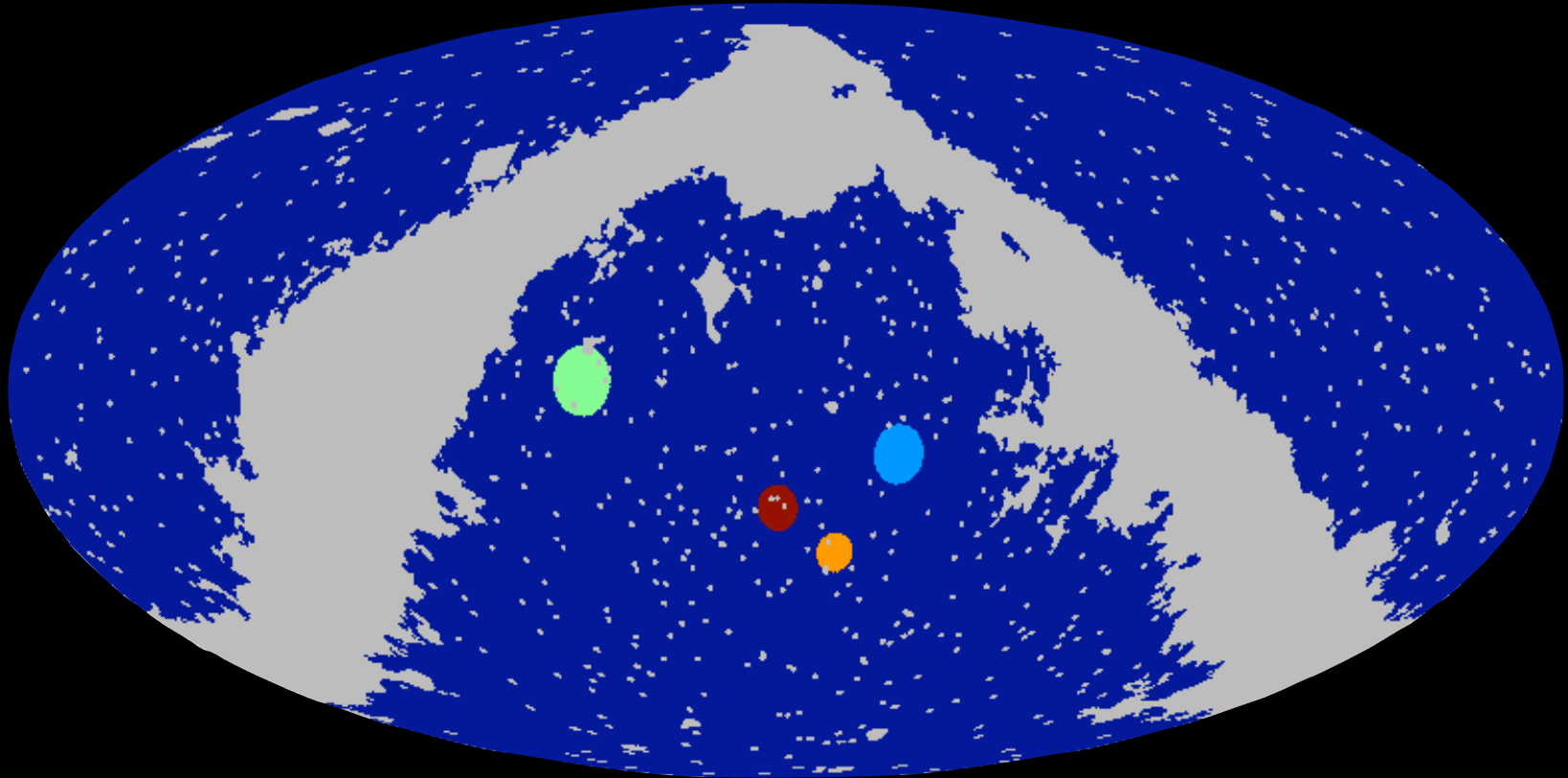
What would we learn about eternal inflation?

- Theory predicts **number of expected collisions** and **strength of each collision** given:
 - ▶ properties of underlying potential (energy scales of minima and potential barriers)
 - ▶ number of e-folds of inflation inside our bubble.

$$N \propto \frac{\lambda}{H_F^4} \left(\frac{H_F}{H_I} \right)^2 \sqrt{\Omega_\kappa}$$

Work In Progress I

- Evidence ratios are currently confined to **patches**



- Theories will predict number on **full-sky** (LCDM)

Work In Progress II

- How do we relate patch evidences to full-sky?
- In the case of one blob only:

$$\Pr(\bar{N}_s | 1, \mathbf{d}, f_{\text{sky}}) = \Theta(\bar{N}_s) f_{\text{sky}} e^{-f_{\text{sky}} \bar{N}_s} \frac{1 + f_{\text{sky}} \bar{N}_s E_b / L_b(\mathbf{0})}{1 + E_b / L_b(\mathbf{0})}$$

- More generally:

$$\Pr(\bar{N}_s | N_b, \mathbf{d}, f_{\text{sky}}) \propto$$

$$\Theta(\bar{N}_s) e^{-f_{\text{sky}} \bar{N}_s} \sum_{N_s=0}^{N_b} \frac{(f_{\text{sky}} \bar{N}_s)^{N_s}}{N_s!} \sum_{b_1, b_2, \dots, b_{N_s}=1}^{N_s} \left\{ \prod_{s=1}^{N_s} \frac{E_{b_s}}{L_{b_s}(\mathbf{0})} \prod_{i,j=1}^{N_s} (1 - \delta_{s_i, s_j}) \right\}$$

Summary

- Detecting bubble collisions in CMB: dramatic signature of pre-inflationary physics and the Multiverse.
- An automated pipeline to look for bubble collisions in the CMB without being biased by *a posteriori* selection effects.
- Applied to WMAP7 data, **no “smoking gun” causal edge signature found**: leads to bounds on parameter space.
- Four features **consistent with bubble collisions** identified.
- Planck will be able to corroborate through increased resolution (3X) and sensitivity (order of magnitude) and counterpart polarization signal (Czech et al 2010).